

Institute of Solid State Physics, NAWI Graz, Graz University of Technology, Austria

Keywords: Autonomous Assembly, Molecular Manipulation, Artificial Intelligence, Machine Learning, Reinforcement Learning

Motivation

<u>Challenge</u>: Moving and re-orienting molecules on a surface with high reliability is non-trivial and difficult to achieve. The interaction process is non-intuitive and therefore the outcome of an action is hard to predict.

<u>Goal</u>: Constructing molecular nanostructures by arranging and orienting molecules at will. This will lead to physical insight into molecule-molecule and molecule-substrate interactions.

Design of the Artificial Intelligence

Design of the Environment

Manipulate molecule along a predefined race-track

No contact required

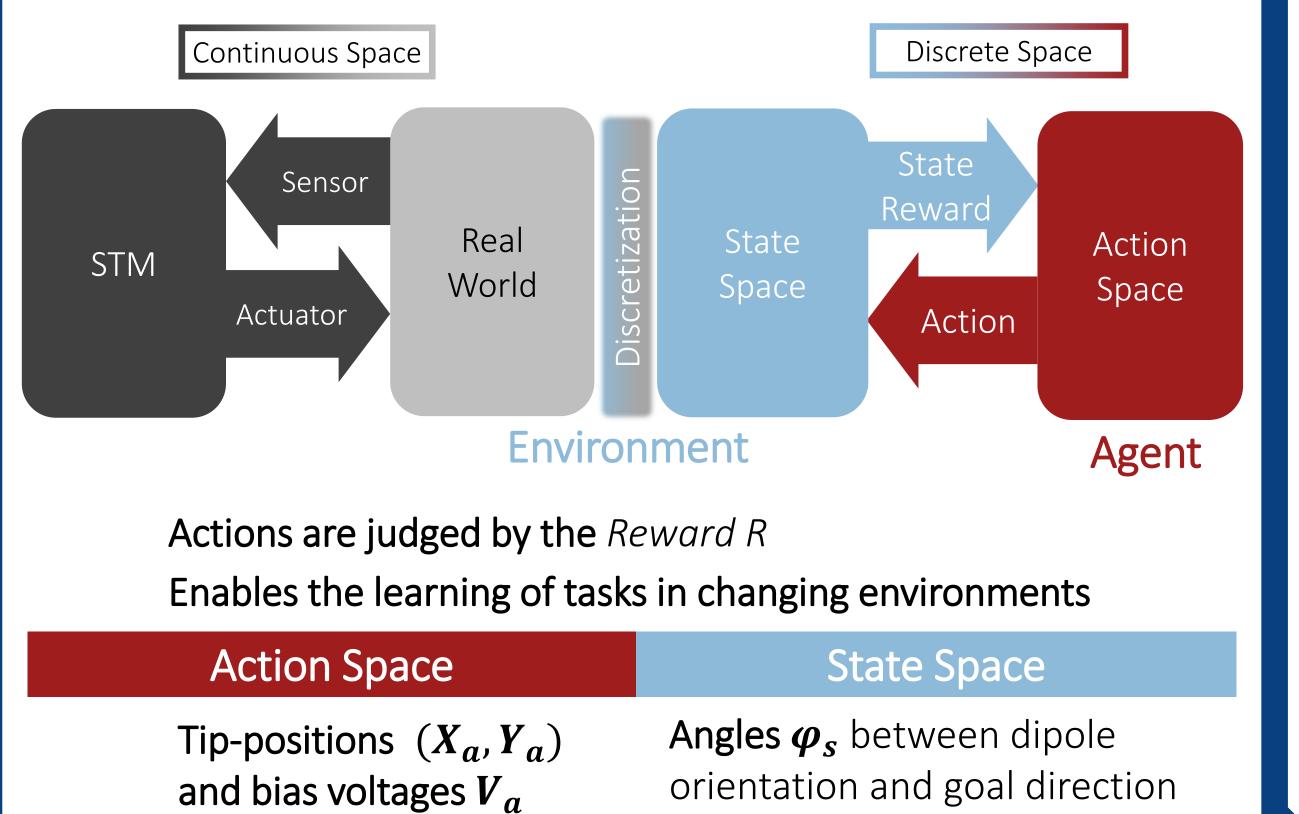


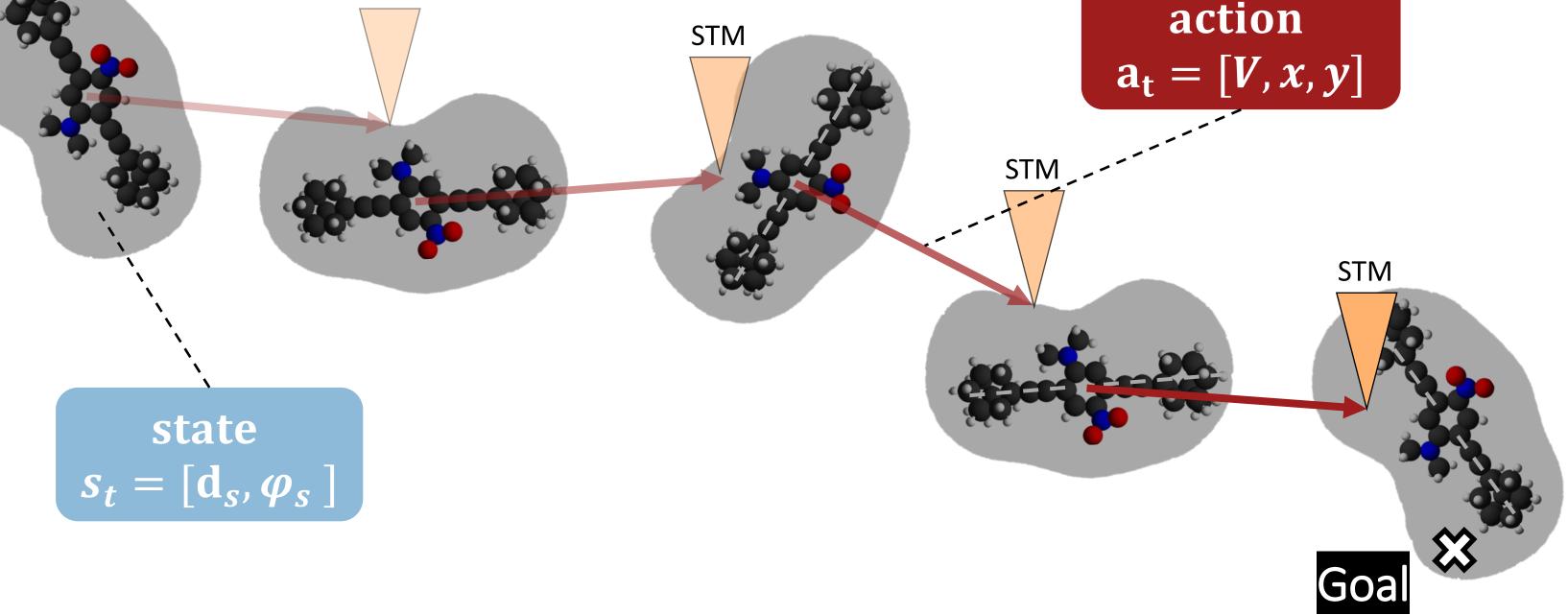


Approach: An Artificial Intelligence is used to learn molecular manipulations by interacting with the molecule and achieve certain objectives.

Reinforcement Learning

Reinforcement learning is mapping states to actions





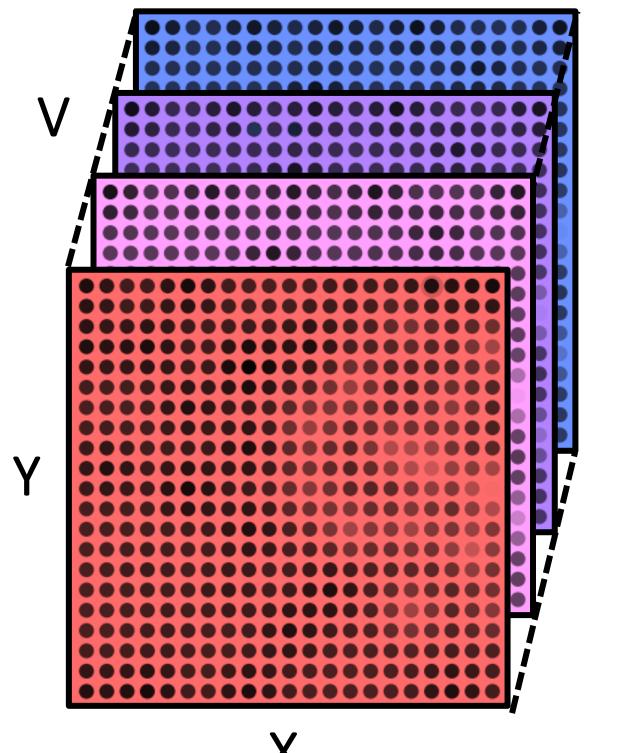
The Q-Learning Algorithm

Q-Learning is an off-policy temporal difference (TD)-control algorithm

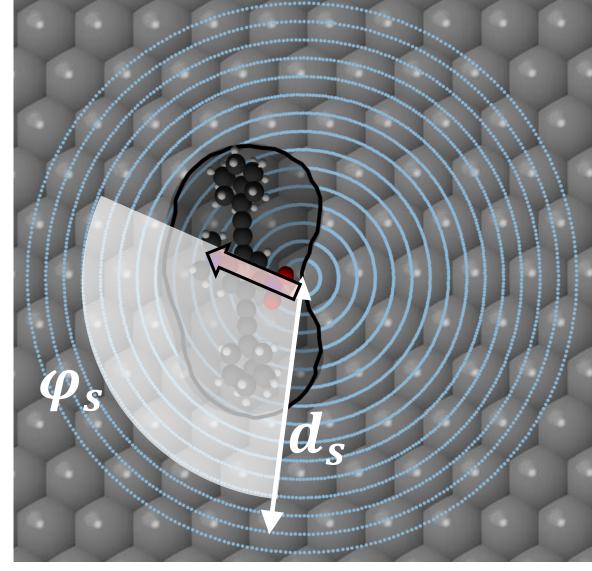
 $\mathbf{Q}^{\text{new}}(\mathbf{s}_t, \mathbf{a}_t) \leftarrow \mathbf{Q}(\mathbf{s}_t, \mathbf{a}_t) + \alpha \left(\mathbf{R}_{t+1} + \gamma \max_{\mathbf{a}} \mathbf{Q}(\mathbf{s}_{t+1}, \mathbf{a}) - \mathbf{Q}(\mathbf{s}_t, \mathbf{a}_t) \right)$

ε-greedy strategy:

- Exploration: select actions based on highest uncertainty of Gaussian Process Regression
- Exploitation: select best-known action



Distance d_s between molecular pivot point and goal position



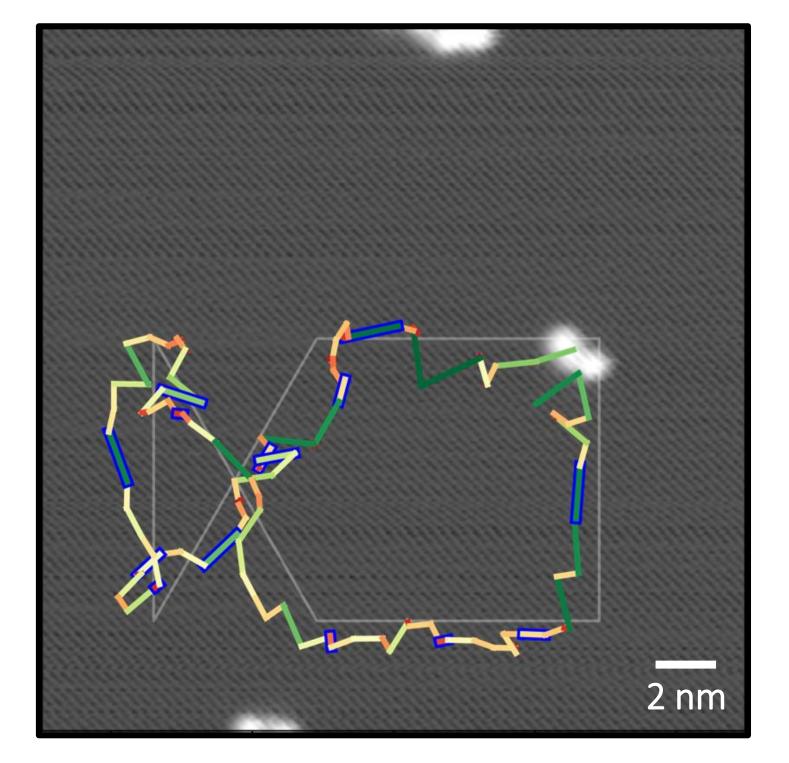
Reward

The *reward* dictates the behavior of the agent

$$R(\Delta x) = \begin{cases} -1 & , \Delta x < d_{min} \\ \frac{\Delta x}{d_{s_max}} & , d_{min} < \Delta x \text{ and } \frac{\Delta x}{d_{s_max}} \le 1 \\ 1 & , \frac{\Delta x}{d_s} > 1 \end{cases}$$

Results

1. Artificial Intelligence maneuvers molecule along a trajectory



2. Gain physical insights of tip-molecule interactions

