

Dynamic Simulation of the Imbalance Netting Process and Cross-Border Activation of the Automatic Frequency Restoration Process

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Faculty of Electrical Engineering and Computer Science 16. Symposium Energieinnovation Graz/Austria, 12. – 14. February 2020



INTRODUCTION



Frequency control

- Imbalance between production and consumption causes frequency deviation from nominal value.
- The size and duration of the frequency deviation must stay within given target values.



Nominal frequency

Load control between Control Areas (CAs)

- The production within the CA must be controlled in order to maintain **scheduled power interchanges** between CAs due to the tie-lines.
- Deviation from scheduled power interchanges may lead to additional power flows that can exceed the **transmission capacities** of the tie-lines.

Load-Frequency Control (LFC) decreases:

• Frequency deviations

 $\Delta f_i = f_{\mathrm{a}i} - f_{\mathrm{s}i}$

• Interchange power variations

 $\Delta P_i = P_{\mathrm{a}i} - P_{\mathrm{s}i}$

• Area Control Error is given as

$$ACE_{i}' = \Delta P_{i} + B_{i} \Delta f_{i}$$

- P_{ai} and f_{ai} measured values
- P_{si} and f_{si} scheduled values
- B_i frequency bias coefficient
- LPF Low Pass Filter
- PI Proportional-Integral Controller
- SH Sample and Hold (2 s)
- ΔP_{sci} Scheduled Control Power
- ΔP_{ei} Electrical Control Power



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- Implementation of INP in LFC structrure
- Input variable is demand power ۲

$$P_{\mathrm{d}i}' = \Delta P_{\mathrm{e}i} - ACE_i$$

Output variable is correction power ۲



 $P_{\mathrm{d}N}$

- Maximal compensation with a limit of P_{di} and the limit of available transmission capacity P_{ATCii} . •
- Proportional to imbalance distribution is used. ۲

Objective of INP

- To **compensate** power deviations between CAs with **opposite signs**.
- To eliminate the activation of control reserve with opposite signs.
- To **reduce** the activation of secondary control reserve.

Economical view

- Developed due to the **high cost** of balancing energy.
- To **reduce** power deviations between CAs.
- By regulating the activation of the balancing energy between CAs, **high economic savings** are possible.

Technical view

• **Release** of control reserve and reduction of balancing energy.

- **Physical** connection between CA₁-CA₂ and CA₂-CA₃.
- All three CAs connected with INP optimization through virtual tie-lines.
- **Condition** for INP:

 $(sign)P_{d1} \neq (sign)P_{d2} \neq (sign)P_{d3}$



Figure 3: Steady-state correction value calculation with INP optimization.



- Implementation of the cross-border activation of aFRP in LFC structrure
- Input variable is demand power

$$P_{\mathrm{d}i}^{*} = \Delta P_{\mathrm{e}i} - ACE_{i}$$

Output variable is correction power



aFRP

 P_{dN}^{*}

Maximal compensation with a limit of P_{di} and the limit of available transmission capacity P_{ATCii} . ۲

Objective of the cross-border activation of aFRP

- To **compensate** power deviations between CAs with **equal signs**.
- To activate the secondary control reserve in neigbouring CAs.
- To **reduce** the activation of secondary control reserve in its own CA.

Economical view

- Developed due to the additional **cost optimization** and **high cost** of balancing energy.
- By activating the secondary control reserve in neigbouring CAs, high economic savings are possible.

Technical view

• **Release** of control reserve and reduction of balancing energy.

- **Physical connection** between CA_1 - CA_2 and CA_2 - CA_3 .
- All three CAs connected with aFRP optimization through virtual tie-lines. •
- **Condition** for aFRP: •
 - $(sign)P_{d1} = (sign)P_{d2} = (sign)P_{d3}$

$$CA_1$$
, CA_2 and $CA_3 -$ **short** \rightarrow **import**

CA₃ activated: • **0.3***P*_{cor3} in CA₁ in CA₂



Figure 5: Steady-state correction value calculation with aFRP optimization.





Figure 6: Block diagram of a single *i*-th CA.

TESTING CASES

- **Separate dynamic simulations** for the system with INP and **separate** for the system with aFRP.
- Step changes of loads for three CAs with INP
 - Case 1: at t = 10 s, $\Delta P_{L1} = -0,06$ pu, $\Delta P_{L2} = -0,04$ pu and $\Delta P_{L3} = 0,08$ pu



Figure 7: Step change of ΔP_{Li} used in numerical simulations for three CAs with aFRP.

Step changes of loads for three CAs with cross-border activation of aFRP

- Case 1: at t = 10 s, $\Delta P_{L1} = 0,04$ pu, $\Delta P_{L2} = 0,06$ pu in $\Delta P_{L3} = 0,08$ pu
- Case 2: at t = 100 s, $\Delta P_{L1} = -0.04$ pu, $\Delta P_{L2} = -0.06$ pu in $\Delta P_{L3} = -0.08$ pu



Figure 8: Step change of ΔP_{Li} used in numerical simulations for three CAs with INP.

RESULTS TO STEP CHANGES OF LOADS WITH INP

- Frequency deviation Δf_i , area Control error ACE_i and scheduled control power ΔP_{sci}
- Reduced Δf_i in Case 1, increased absolute value of Δf_2 and Δf_3 in Case 2 with INP
- Reduced ACE_i and ΔP_{sci} with INP



"wo" is without INP and "w" is with INP.



RESULTS TO STEP CHANGES OF LOADS WITH INP

- Electrical control power ΔP_{ei} , interchange power variation ΔP_{i} , demand power P_{di} and correction power P_{cori}
- Reduced ΔP_{e_i} , increased ΔP_i with INP
- Opposite sign of P_{di} and P_{cori}



RESULTS TO STEP CHANGES OF LOADS WITH aFRP

- Frequency deviation Δf_i , area control error ACE_i and scheduled control power ΔP_{sci}
- Reduced Δf_i with INP
- Increased ACE₁ and ACE₂, reduced ACE₃
- Increased ΔP_{sc1} and ΔP_{sc2} , reduced ΔP_{sc3}



- $0.7P_{corj}^{*}$ in CA₁
- $0.3P_{corj}^*$ in CA₂





RESULTS TO STEP CHANGES OF LOADS WITH aFRP

- Area control error ACE_i and scheduled control Power ΔP_{sci}
- Simulation time 900 s
- Steady-state value

- CA₃ activated:
- 0.7P_{corj}^{*} in CA₁
 0.3P_{cori}^{*} in CA₂



- Electrical control power ΔP_{ei} , interchange power variation ΔP_{i} , demand power P_{di} and correction power P_{cori}
- Increased ΔP_{e1} and ΔP_{e2} , reduced ΔP_{e3} , increased ΔP_i with aFRP
- Opposite sign of P_{di} and P_{cori}



"wo" is without INP and "w" is with INP.

 CA_3 activated:

- $0.7P_{corj}^*$ in CA₁
- $0.3P_{corj}^*$ in CA₂



CONCLUSION

- INP and cross-border activation of aFRP **reduce** frequency deviation.
- Cases of frequency quality **deterioration** can occur.
- Area control error, scheduled control power and electrical control power are:
 - Reduced with INP.
 - **Reduced** with cross-border activation of aFRP, when CA activates the secondary control reserve in neigbouring CAs.
- **Smaller** activation of secondary control reserve.
- INP and cross-border activation of aFRP:
 - **Release** regulating reserve.
 - **Reduce** balancing energy.
- **Future work** should focus on the dynamic dimensioning of regulating reserve with respect to INP and cross-border activation of aFRP.
- Possible over dimension of regulating reserve could be decreased.





Thank you for your attention!



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