



24th Computer Vision Winter Workshop 2019

6th – 8th February 2019, Stift Vorau, Austria

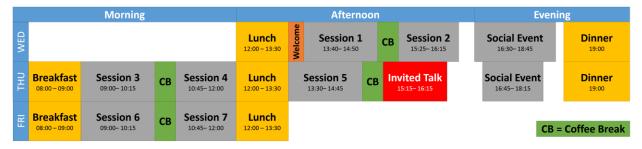
The **24**th **Computer Vision Winter Workshop (CVWW 2019),** taking place at Stift Vorau, Austria, is organized by the Institute of Computer Graphics and Vision at Graz University of Technology. The Computer Vision Winter Workshop is the annual meeting of computer vision research groups located in Graz, Ljubljana, Prague, and Vienna. The main goal of this workshop is to communicate fresh scientific ideas within these four groups and to provide conference experience to PhD students. However, the workshop is open to everyone, which can be seen from many international contributions and attendees.

After a double-blind full paper review process by an international programme committee, finally, seven original works have been accepted for publication. They will be presented at the workshop as oral presentations. In addition, we are happy that **Gabriel J. Brostow** (University College London) accepted our invitation to give a talk on **Self-supervision for 3D Shape and Appearance Modeling**. The workshop program is completed by 13 further oral presentations.

The co-chairs of the workshop would like to thank the members of the program committee for their work, support and feedback.

Friedrich Fraundorfer Peter M. Roth Fabian Schenk

Program Overview



24th Computer Vision Winter Workshop 2019, Stift Vorau, Austria, 6th – 8th February 2019



Wednesday, 06.02.2019



| | Morning | Afternoon | | Even | Evening | | |
|--------------|---|------------------------|---------------------------------|-------|--------------------------|-----------------------------|------------------------|
| WED | | Lunch 12:00 - 13:30 | Session 1 13:40-14:50 | СВ | Session 2 15:25-16:15 | Social Event 16:30-18:45 | Dinner 19:00 |
| 12:00-13:25 | Lunch | | | | | | |
| 13:30- 13:40 | Welcome Speech by the Organizers | | | | | | |
| 13:40-14:50 | Session 1 – Computer Vision in the Wild | | | | | | |
| 13:40-14:05 | Leveraging Outdoor Webcams for Local Descriptor Learning | | | | | | |
| | Milan Pultar, Dmytro Mishkin, Jiri Matas | | | | | | |
| 14:05-14:30 | Image Retrieval under Varying Illumination Conditions | | | | | | |
| 14:30-14:55 | Tomáš Jeníček, Ondrej C Quantitative Affine Feat | | mparison Ba | od or | Pool World | Imagos Takon hu a | Quadcantar |
| | Zoltán Pusztai, Levente F | | | eu oi | i Real-world | iniages laken by a | Quadcopter |
| | zonan i usztal, zevente i | lajuel | | | | | |
| 14:55-15:25 | Coffee Break | | | | | | |
| 15:25-16:15 | Session 2 – Beyond Computer Vision | | | | | | |
| 15:25-15:50 | Counting slope regions in the surface graphs | | | | | | |
| | Darshan Batavia, Rocio Gonzalez-Diaz, Walter G. Kropatsch, Rocio Moreno Casablanca | | | | | | |
| 15:50-16:15 | Geometric Projection Parameter Consensus: Joint 3D Pose and Focal Length Estimation in the Wild | | | | | | |
| | Alexander Grabner, Pete | r M. Roth, Vince | ent Lepetit | | | | |
| 16:15-16:30 | Preparation for Social Ev | vent | | | | | |
| 16:30-18:45 | Social Event – Sub Terra Vorau, Guided tour through subterranean pathways | | | | | | |
| | Sturdy shoes and warm | | - | | | , | |
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Invited Talk: Self-supervision for 3D Shape and Appearance modeling



Gabriel J. Brostow University College London

A single glimpse is hardly enough to triangulate the 3D shapes of a scene. But many glimpses taken together, can give enough supervision to accomplish interesting tasks, such as depth from a single photo, volume from a single depth, and appearance of objects and scenes from novel viewing angles. In this talk, I will distill the main lessons we have learned recently, in attempting to a) design networks that understand "a bit" about 3D, and to b) train networks to predict depth, or volumes, or appearance, for several application domains. Some details matter, and the data itself is a key ingredient. There is still more exciting work to be done!

This talk will cover equivariance, consistency losses, and some personal views on diversity in predictions.

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Thursday, 07.02.2019

| | Morning Afternoon Evening | | | | | | |
|--------------|---|--|--|--|--|--|--|
| PE Breakfast | Session 3 09:00-10:15 CB Session 4 10:45-12:00 Lunch 12:00-13:30 Session 5 13:30-14:45 CB Invited Talk 15:15-16:15 Social Event 16:45-18:15 Dinner 19:00 | | | | | | |
| 08:00-09:00 | Breakfast | | | | | | |
| 09:00-10:15 | Session 3 – Benchmarks and Datasets | | | | | | |
| 09:00-09:25 | An Unbiased Look at Face Hallucination | | | | | | |
| 09:25-09:50 | Klemen Grm, Martin Pernuš, Leo Cluzel, Simon Dobrisek, Vitomir Struc SyDD: Synthetic Depth Data Randomization for Object Detection using Domain-Relevant Background | | | | | | |
| 09:50-10:15 | Stefan Thalhammer, Kiru Park, Timothy Patten, Markus Vincze, Walter G. Kropatsch | | | | | | |
| 05.50 10.15 | Benchmarking Semantic Segmentation Methods for Obstacle Detection on a Marine Environment Borja Bovcon, Matej Kristan | | | | | | |
| 10:15-10:45 | Coffee Break Group Photo | | | | | | |
| 10:45-12:00 | Session 4 – Space-Time Methods | | | | | | |
| 10:45-11:10 | Situation-Aware Pedestrian Trajectory Prediction with Spatio-Temporal Attention Model Sirin Haddad, Meiging Wu, Wei He, Siew-Kei Lam | | | | | | |
| 11:10-11:35 | A Spatiotemporal Generative Adversarial Network to Generate Human Action Videos | | | | | | |
| | Stefan Ainetter, Axel Pinz | | | | | | |
| 11:35-12:00 | Combining Top-Down and Bottom-Up Processes to Extract Space-Time Volumes of Interest from Video Filip Ilic, Axel Pinz | | | | | | |
| 12:00-13:30 | Lunch | | | | | | |
| 13:30-14:45 | Session 5 – Geometric Vision | | | | | | |
| 13:30-13:55 | Robust Fitting of Geometric Primitives on LiDAR Data | | | | | | |
| 13:55-14:20 | Tóth Tekla MAGSAC: marginalizing sample consensus | | | | | | |
| 14.20 14.45 | Dániel Baráth, Jiri Matas, Jana Noskova | | | | | | |
| 14:20-14:45 | Planar Motion from a Single Affine Correspondence Levente Hajder, Dániel Baráth | | | | | | |
| 14:45-15:15 | Coffee Break | | | | | | |
| 15:15-16:15 | Invited Talk – Self-supervision for 3D Shape and Appearance modeling | | | | | | |
| | Gabriel Brostow – University College London | | | | | | |
| 16:45-18:15 | Social Event - Cider Tasting/Mostverkostung | | | | | | |
| 19:00 | Dinner | | | | | | |



Friday, 08.02.2019

| | Morning | Afternoon | Evening | | | | |
|-------------|--|---|----------------------------------|--|--|--|--|
| Breakfast | Session 6 09:00- 10:15 CB Session 7 10:45- 12:00 | Lunch 12:00-13:30 | | | | | |
| 08:00-09:00 | Breakfast | | | | | | |
| 09:00-10:45 | Session 6 – Visual Learning | | | | | | |
| 09:00-09:25 | Improving CNN classifiers by e | estimating test-time priors | | | | | |
| | Milan Sulc, Jiri Matas | | | | | | |
| 09:25-09:50 | The Human is Always Right: The Cognitive Relevance Transform | | | | | | |
| | Gregor Koporec, Andrej Košir, Aleš Leonardis, Janez Perš | | | | | | |
| 09:50-10:15 | Deep Learning for Surface-Defect Detection | | | | | | |
| | Domen Tabernik, Samo Šela, Jure Skvarč, Danijel Skocaj | | | | | | |
| 10:15-10:45 | Coffee Break | | | | | | |
| 10:45-12:00 | Session 7 – Object Detection and Pose Estimation | | | | | | |
| 10:45-11:10 | Pulling on socks by a force-co | mpliant robot | | | | | |
| | Megumi Miyashita, Vladimír K | ubelka, Vaclav Hlavac | | | | | |
| 11:10-11:35 | Perspective transformation for | or accurate detection of 3D bounding boxes of | vehicles in traffic surveillance | | | | |
| | Viktor Kocur | | | | | | |
| 11:35-12:00 | Object Tracking by Reconstrue | ction with View-Specific Discriminative Correla | tion Filters | | | | |
| | Ugur Kart, Alan Lukezic, Matej | Kristan, Joni-Kristian Kamarainen, Jiri Matas | | | | | |
| | | | | | | | |
| 12:00-12:15 | Closing Ceremony and Awa | ards | | | | | |

12:15-13:30 Lunch