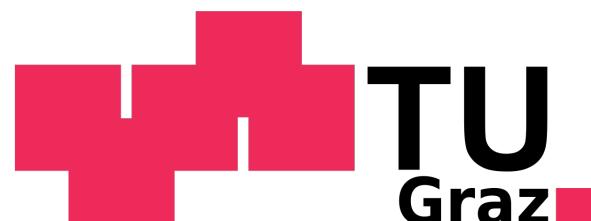


On the Locality of Hall's Theorem

Sebastian Brandt · Yannic Maus · Ananth Narayanan ·

Florian Schager · Jara Uitto

9. Dezember 2024



Contributions

Motivation

Design asymptotically optimal
algorithms in the LOCAL model

$$\Theta(\log n)$$

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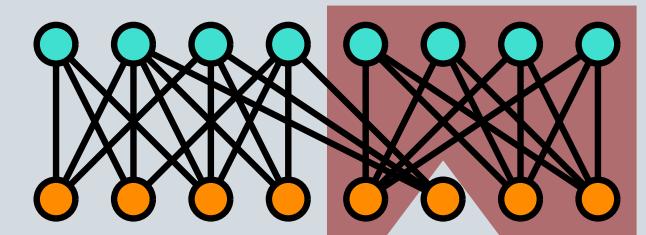
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Algorithm design technique

Distributed Hall's Theorem



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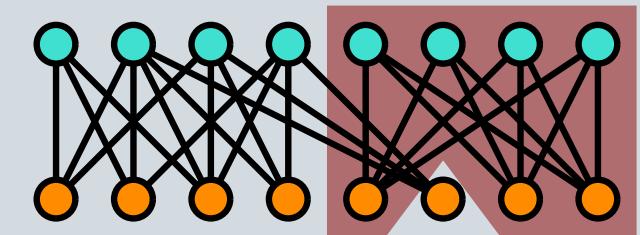
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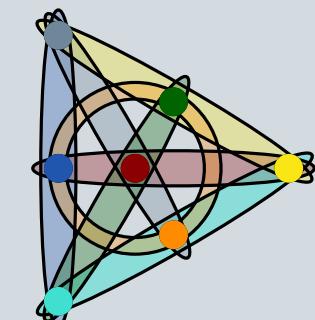
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Application

Hypergraph sinkless orientation



Model of computation

Definition (LOCAL model)

[Linial, 1992]

- communication network is abstracted as an undirected graph $G = (V, E)$
- nodes have unique IDs, edges serve as communication channels
- communication happens in synchronous rounds
- message size and local computation is unlimited
- each node outputs a (local part of a) solution
- time complexity is the number of communication rounds

Asymptotically optimal algorithms in LOCAL

Problem: Sinkless orientation

[Brandt et al. STOC'16]

Input: A Δ -regular graph $G = (V, E)$.

Output: An orientation of the edges such that each vertex has at least one outgoing edge.

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Algorithm design technique

Hall's Theorem

[Hall 1935]

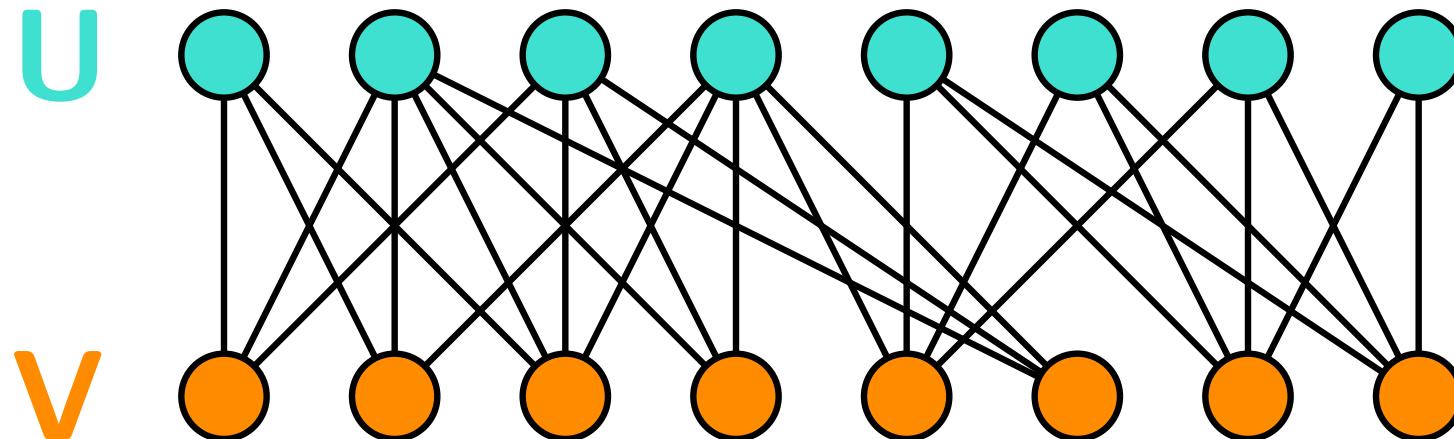
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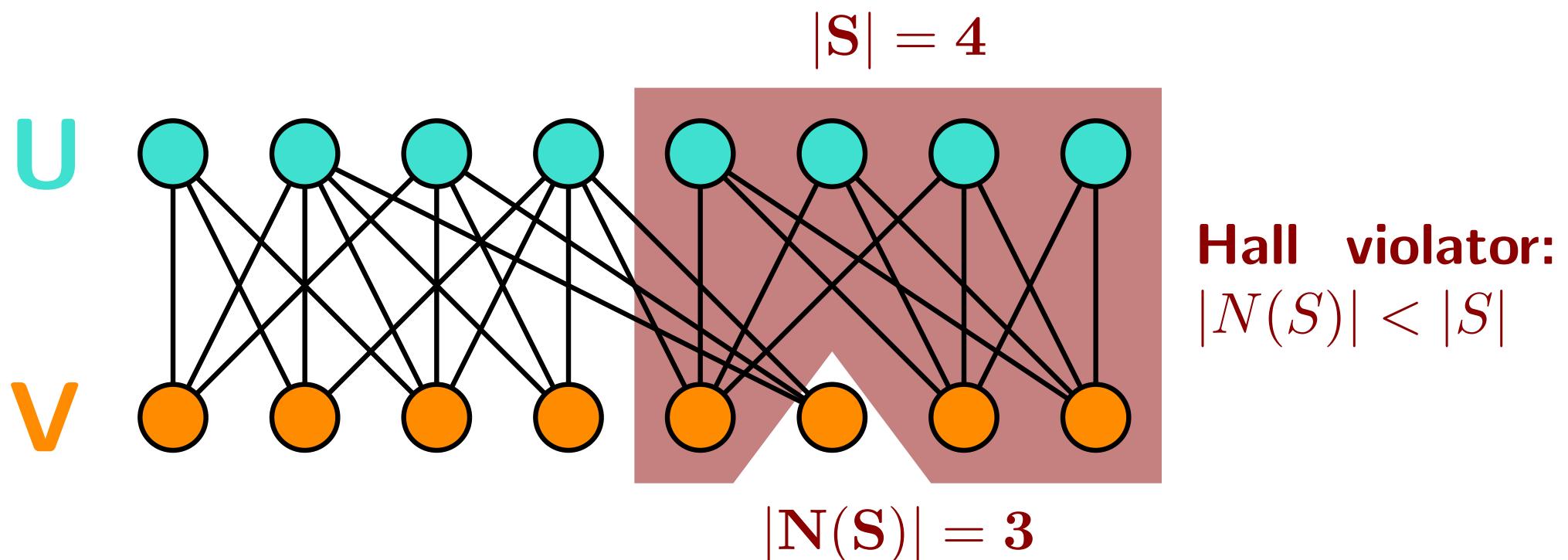


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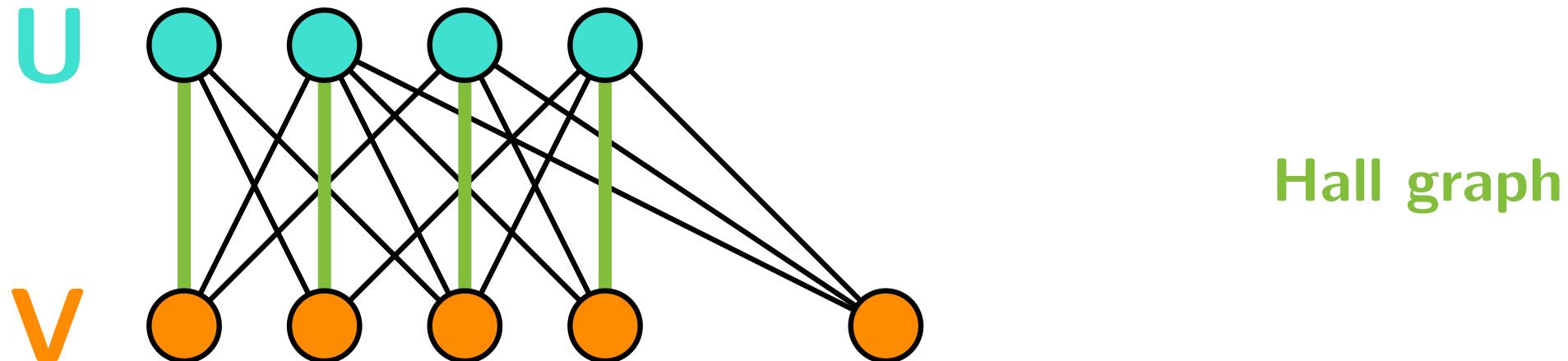


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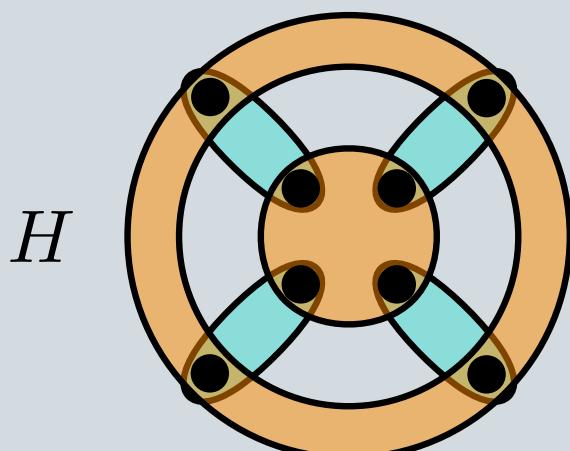
Definition (Hypergraph $H = (V, E)$)

- generalization of a graph, each edge may contain arbitrarily many vertices
- the *degree* $\deg(v)$ of a vertex $v \in V$ is the number of incident edges
- the *rank* $\text{rank}(e)$ of an edge $e \in E$ is the number of vertices in the edge
- $\delta := \min_{v \in V} \deg(v)$ is the minimum degree of H
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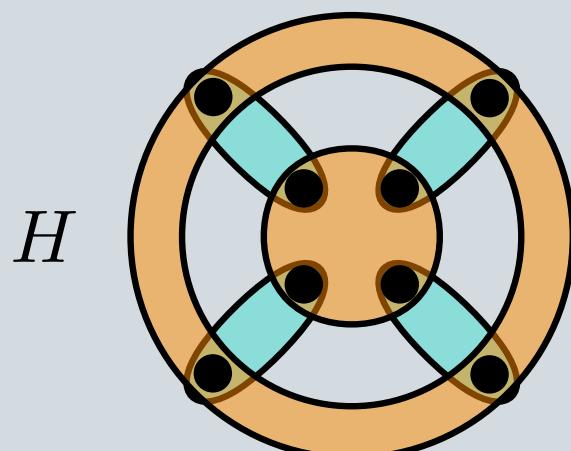
Example ($\delta = 2, r = 4$)



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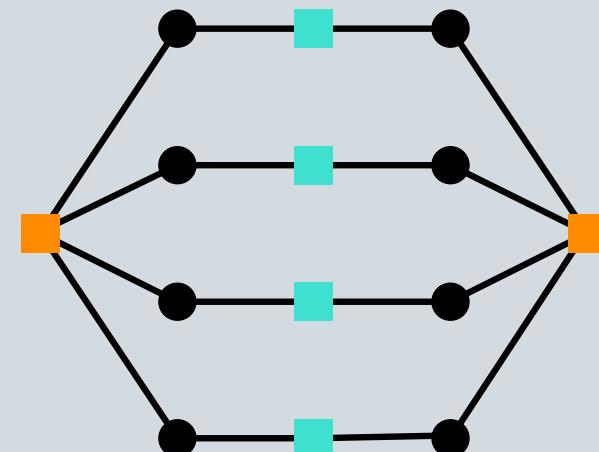
Bipartite representation

$$\mathcal{B}_H = (V, E, F)$$

$$(v, e) \in F$$

\iff

$$v \in e$$



Every vertex is contained in a small-diameter Hall graph

Lemma 1: Many edges

Let $r < \delta$ and $x = \log_{(\delta-1)/(r-1)} n$. For any $v \in V$ there exists a subgraph $(V', E') \subseteq B_x^G(v)$ such that $v \in V'$ and $|E'| \geq |V'|$.

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Lemma 2: Non-empty Hall subgraph

Any non-empty hypergraph $G = (V, E)$ with $|V| \leq |E|$ contains a non-empty Hall subgraph.

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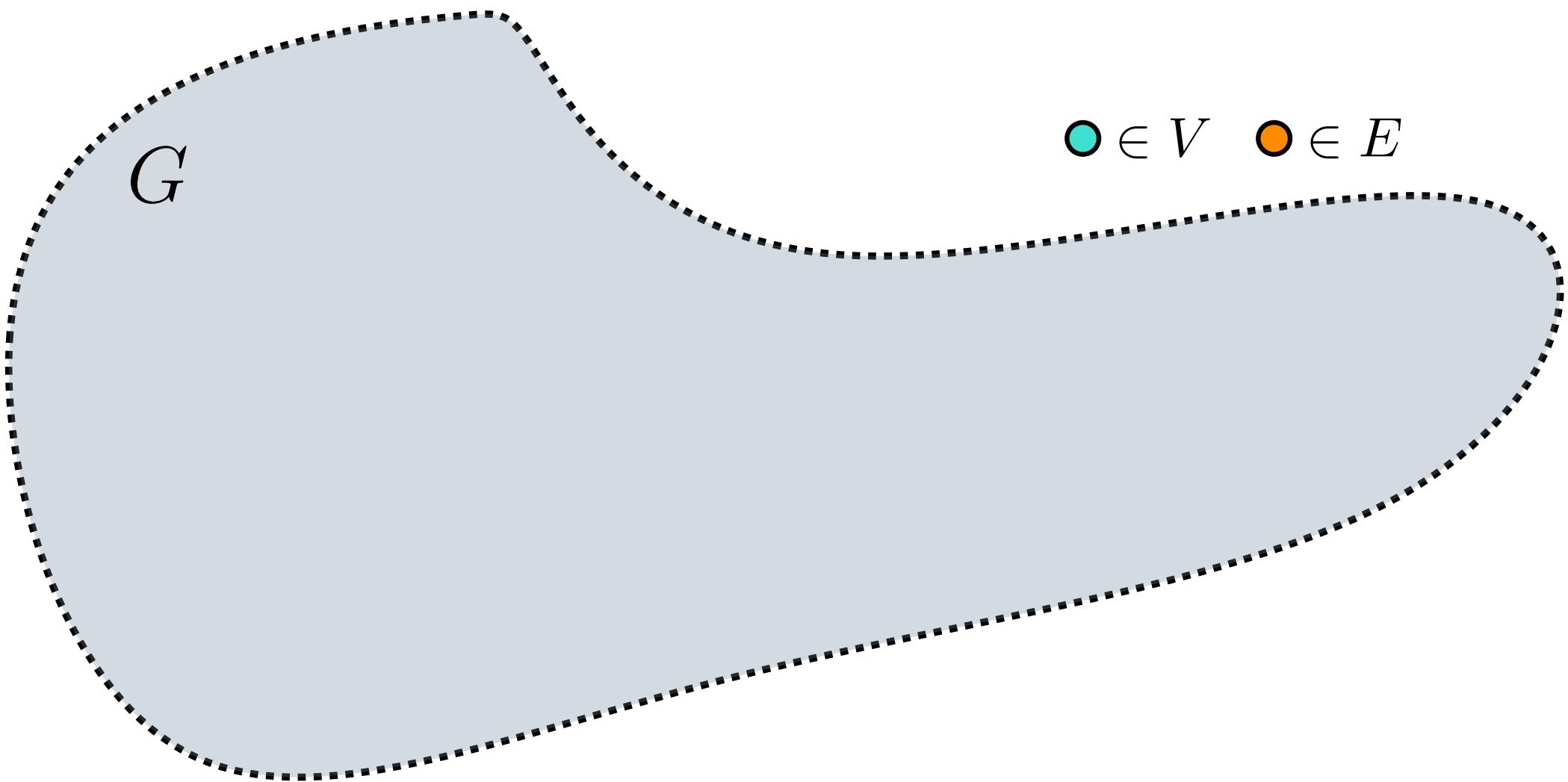
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Distributed Hall's Theorem

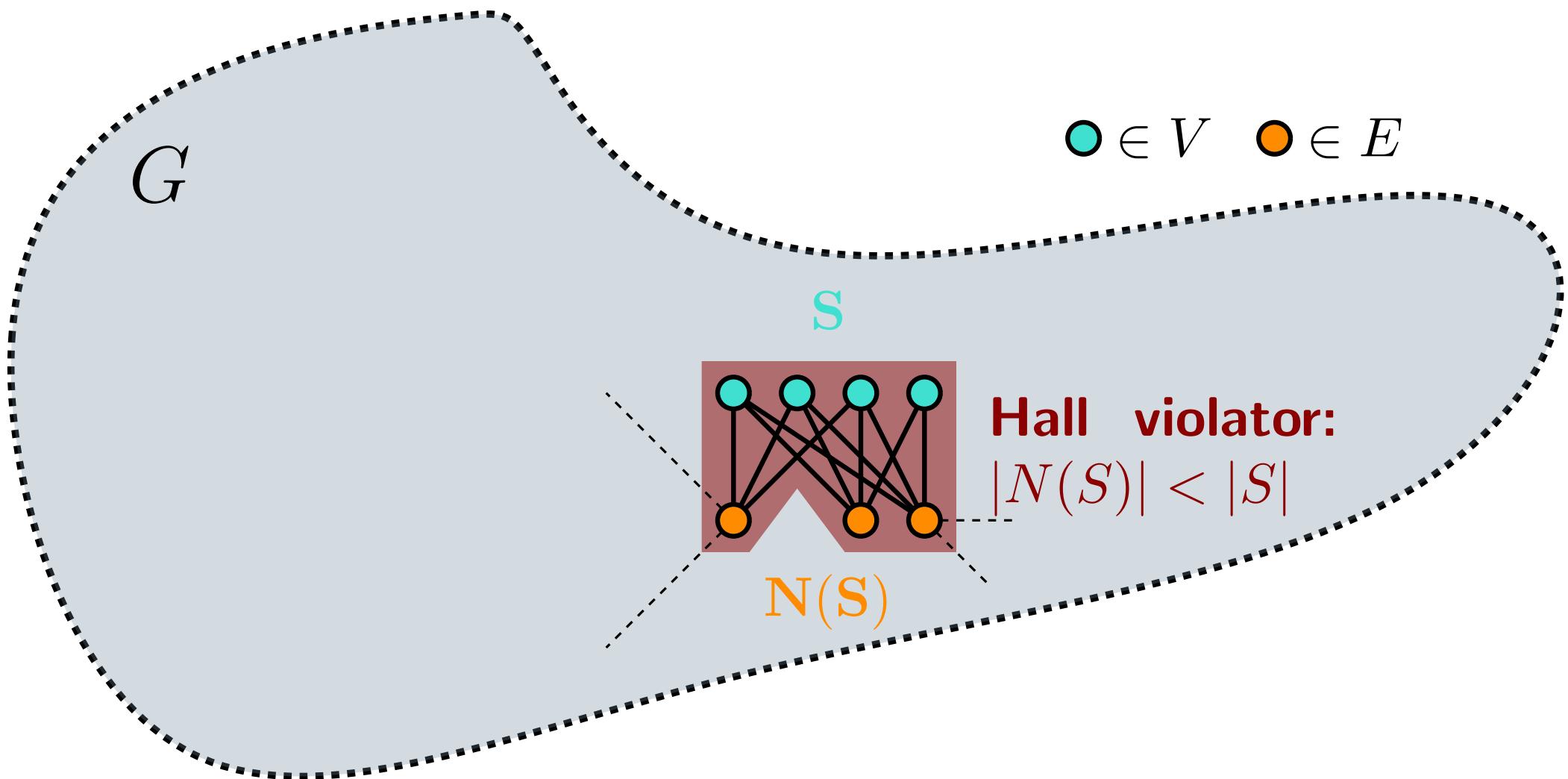
Each node in any n -node hypergraph with minimum degree δ and maximum rank $r < \delta$ is contained in a Hall graph with diameter $\log_{\delta/r} n$.

Non-empty Hall subgraph



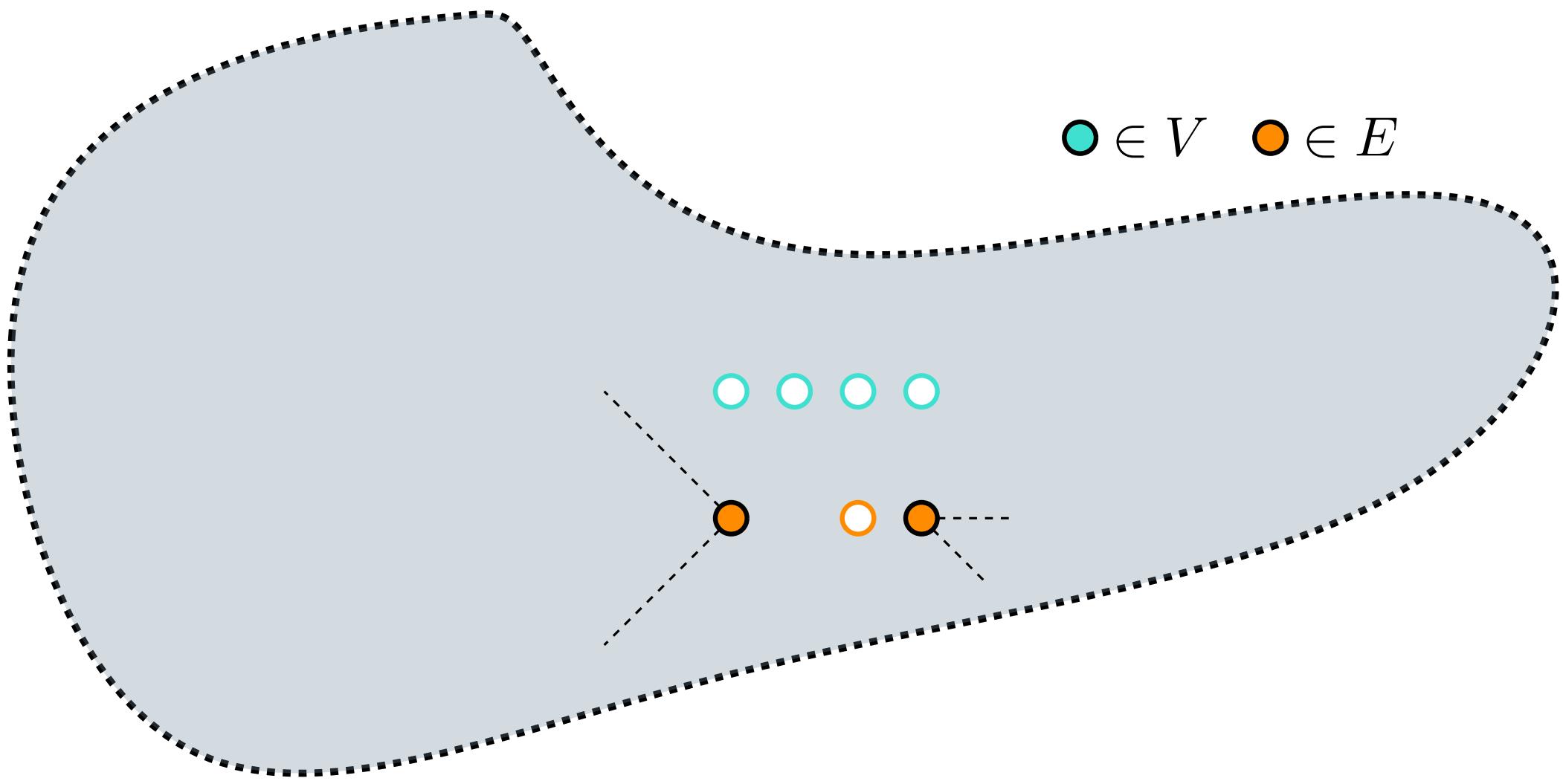
Let $G = (V, E)$ such that $|V| \leq |E|$.

Non-empty Hall subgraph



If G is not a Hall graph, there exists a Hall violator $S \subseteq V$.

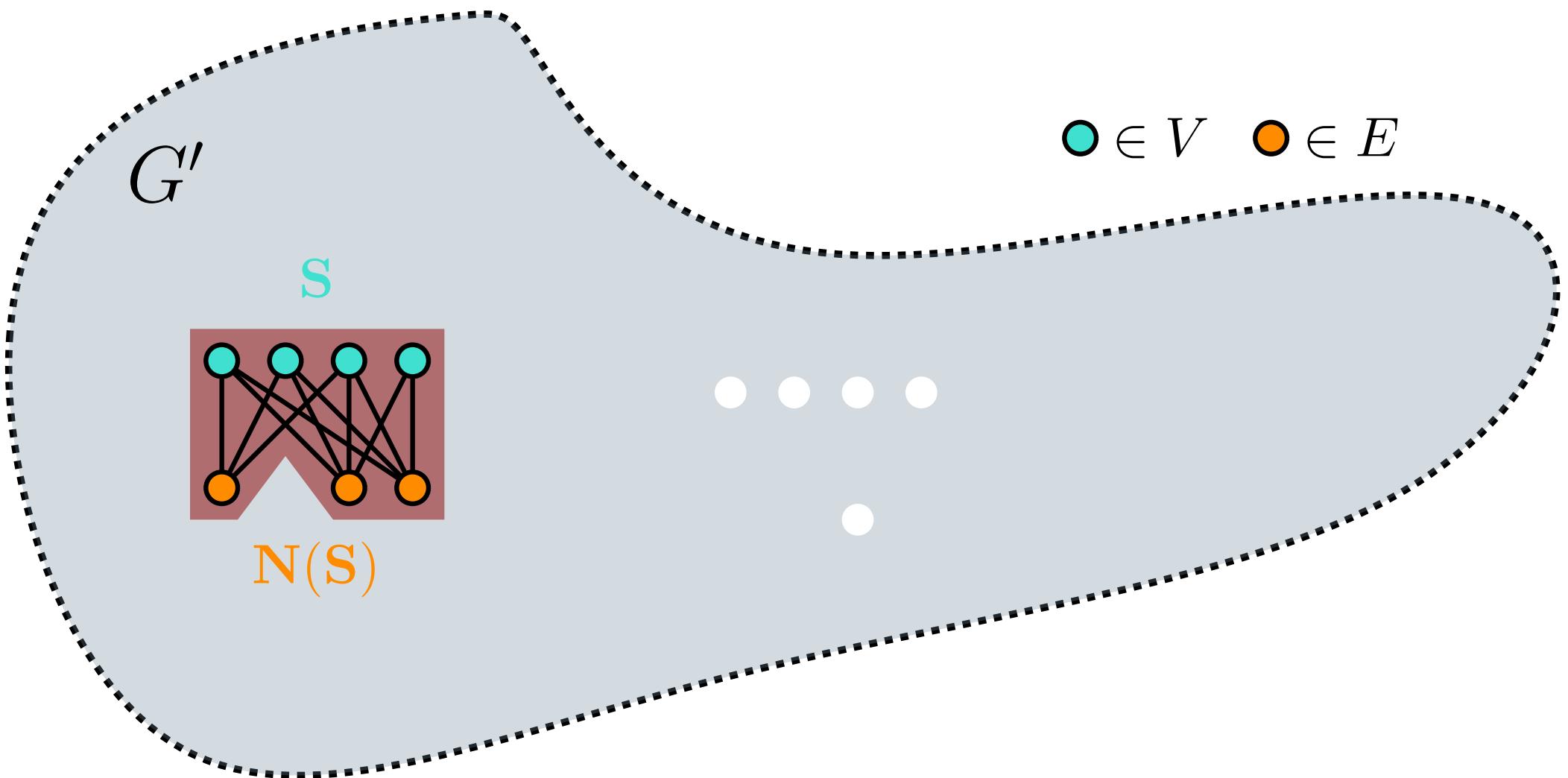
Non-empty Hall subgraph



Define $V' := V \setminus S$ and $E := E|_{V'}$.

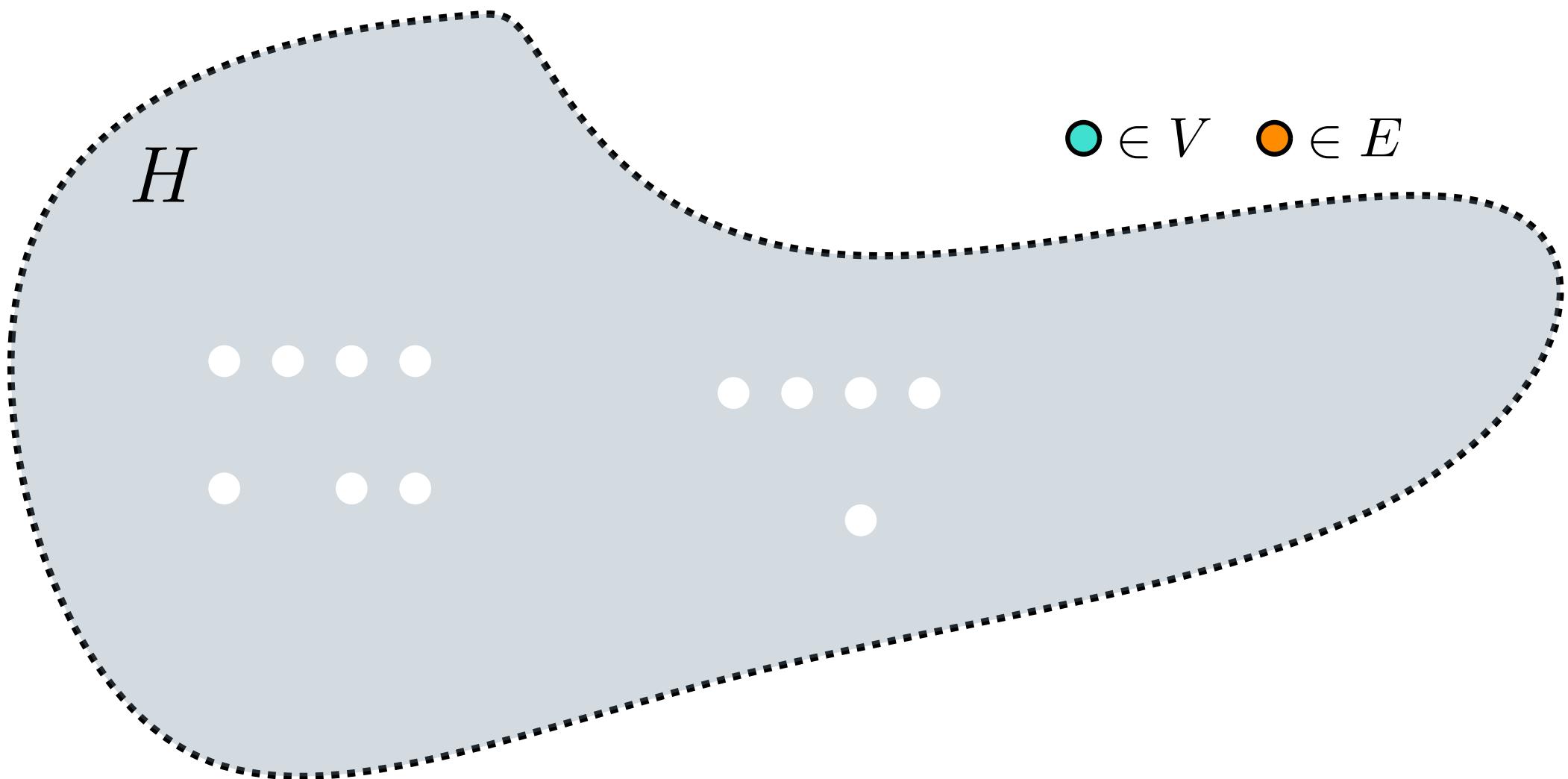
$$|V'| = |V| - |S| < |V| - |N(S)| \leq |E| - |N(S)| \leq |E'|.$$

Non-empty Hall subgraph



Repeat for $G' = (V', E')$.

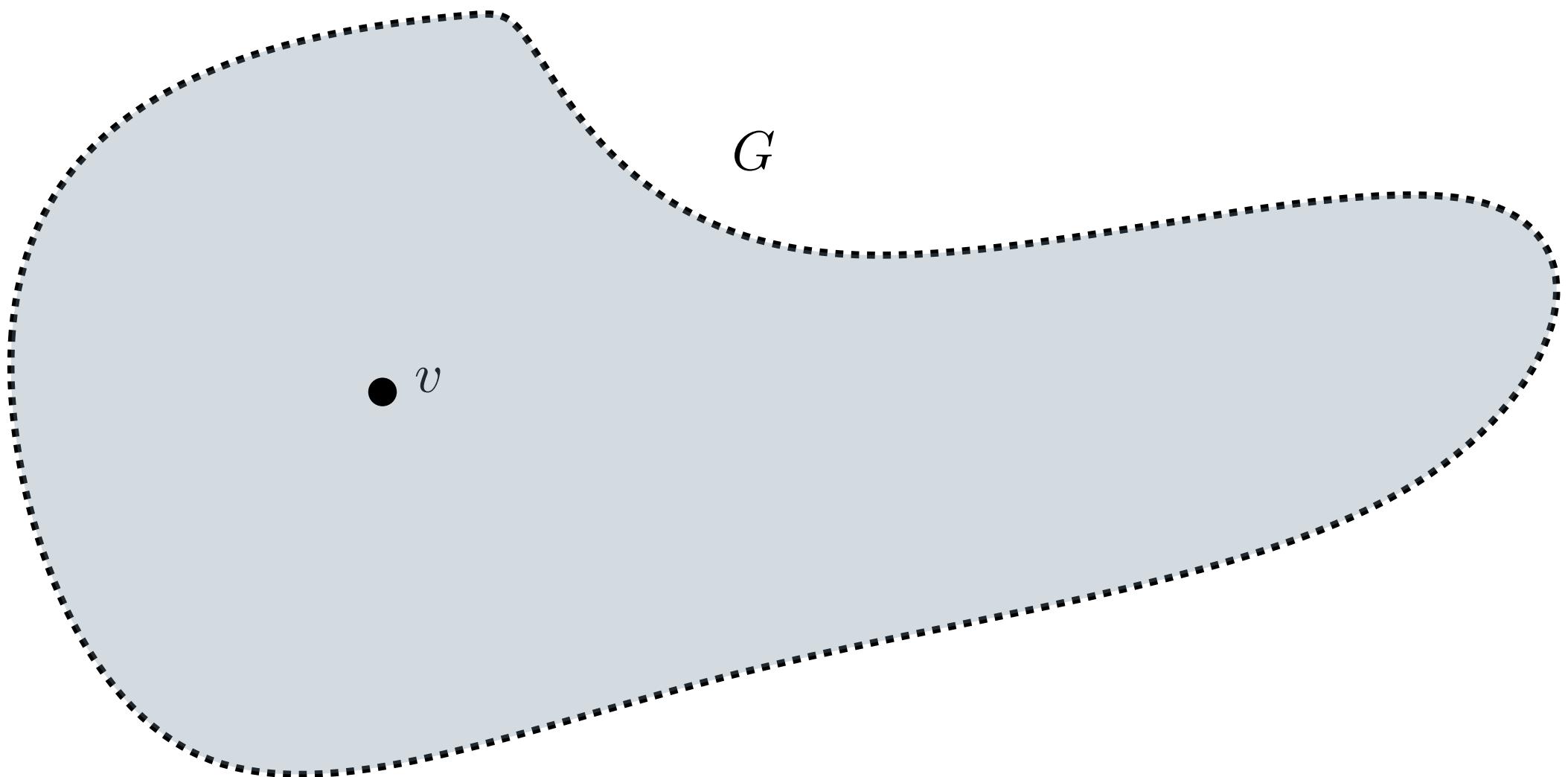
Non-empty Hall subgraph



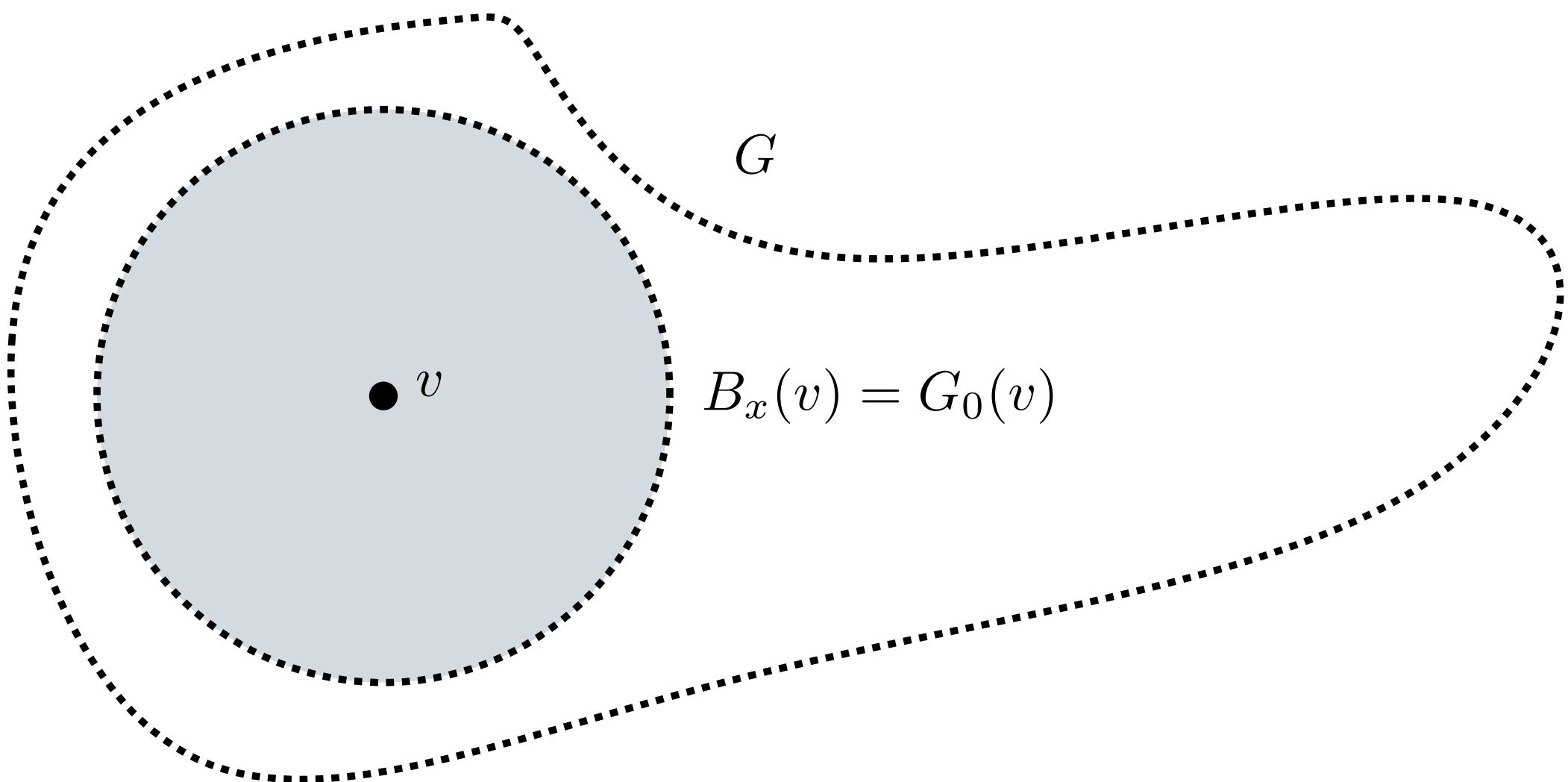
$\bullet \in V$ $\circ \in E$

Since $|V'| < |E'|$, this process cannot end with an empty graph.

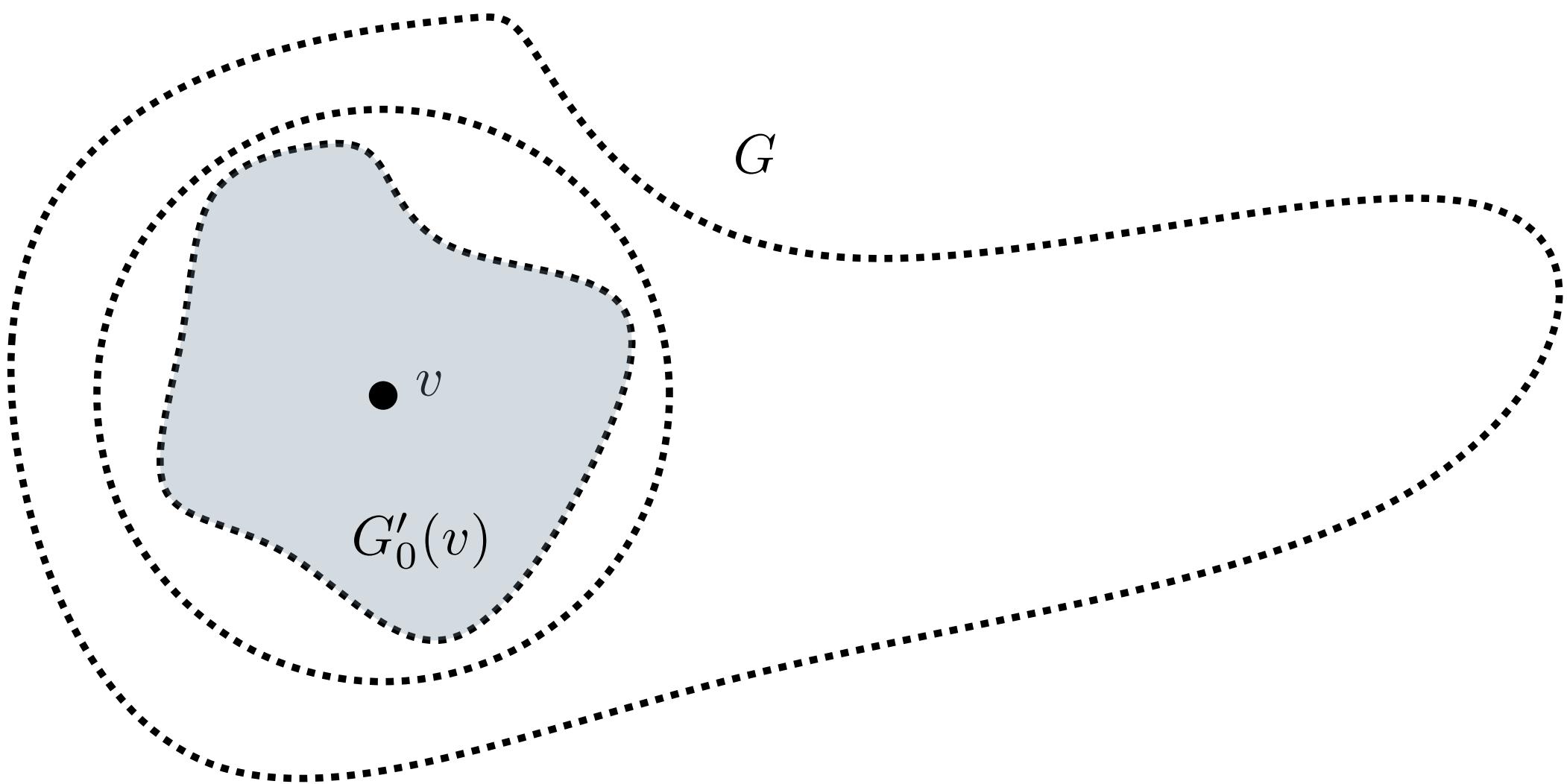
Distributed Hall's algorithm



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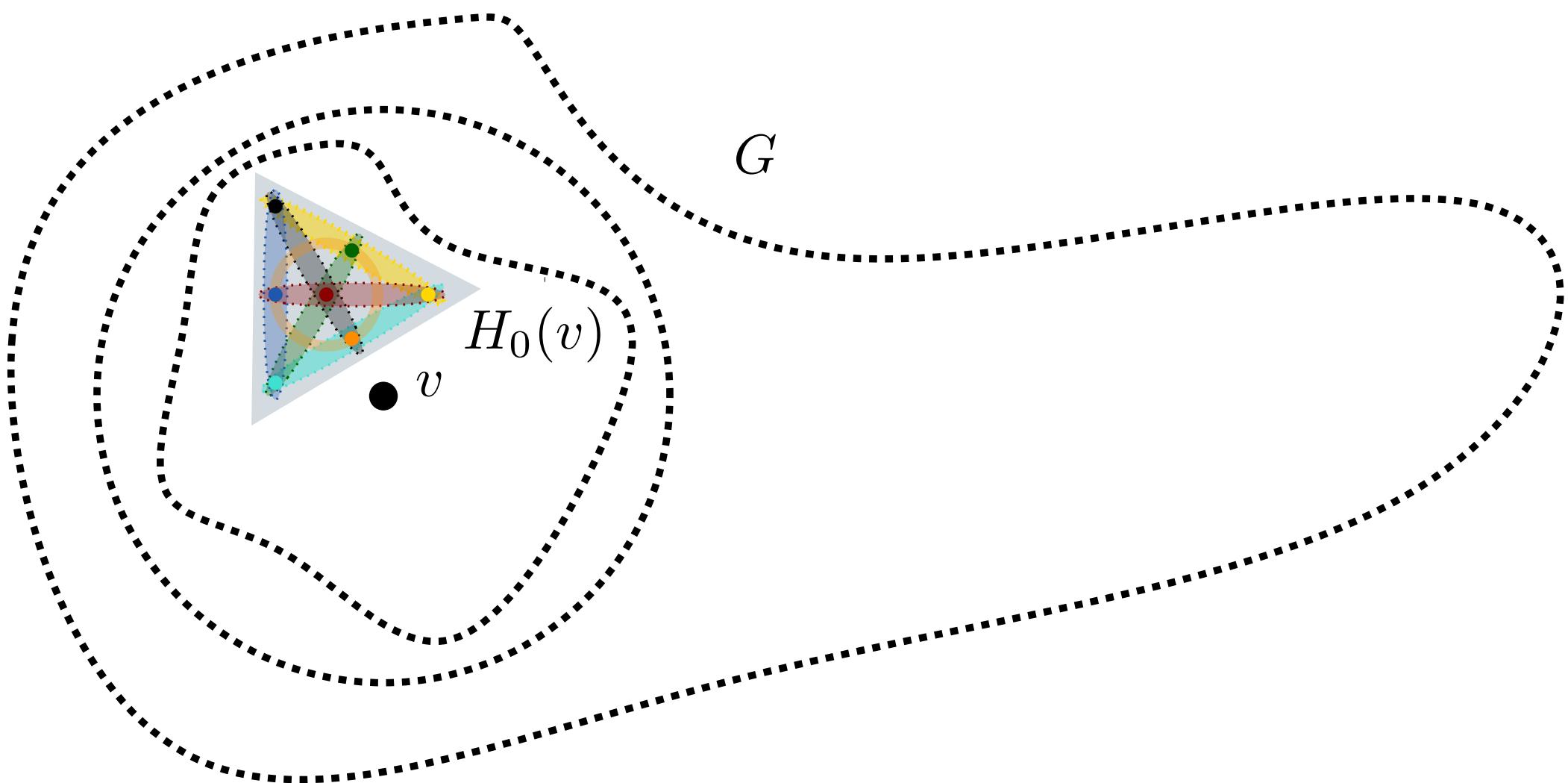


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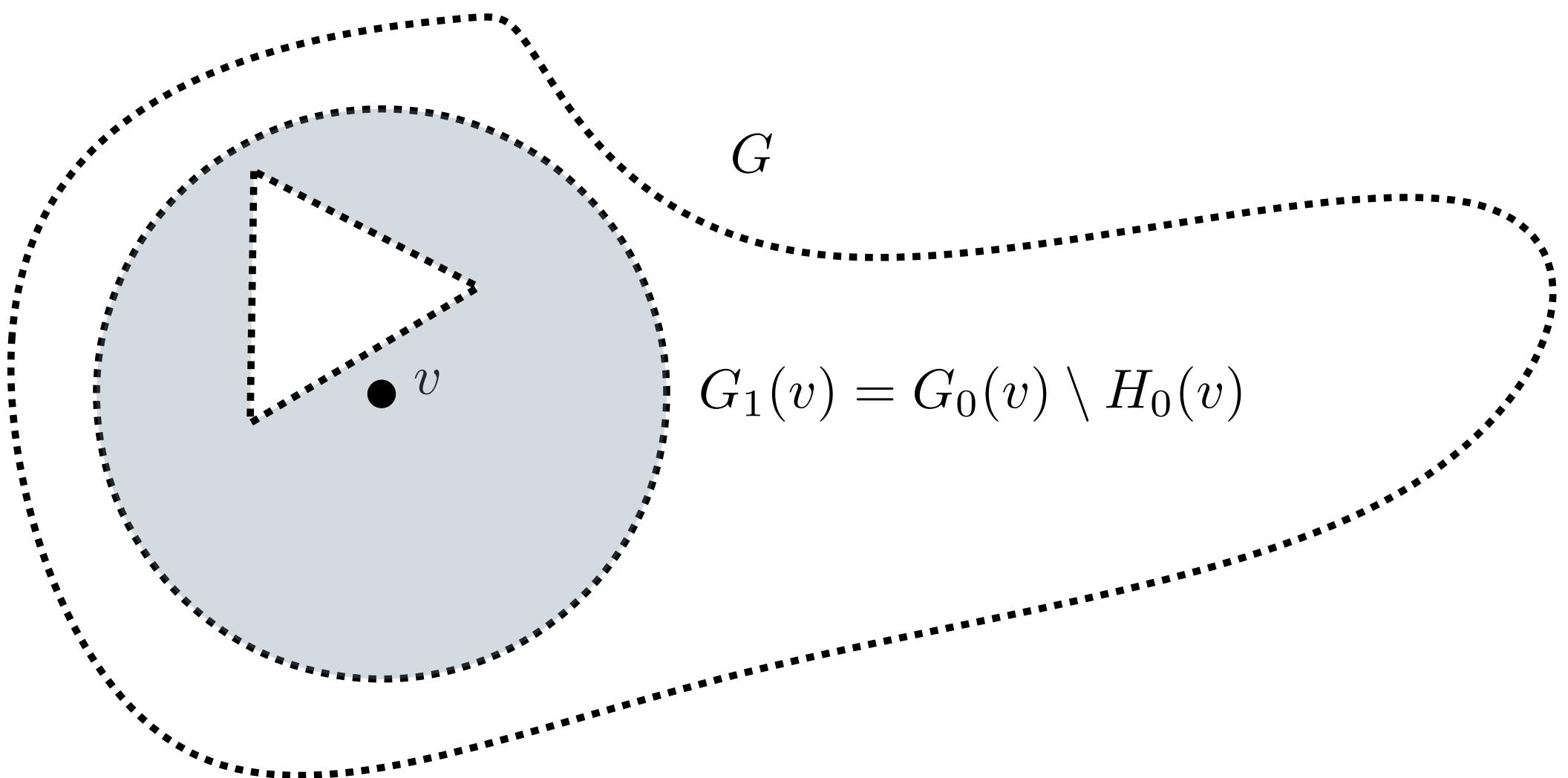
Lemma 1: Find a subgraph $v \in G'_0(v) \subseteq G_0(v)$ with $|V'| \geq |E'|$.

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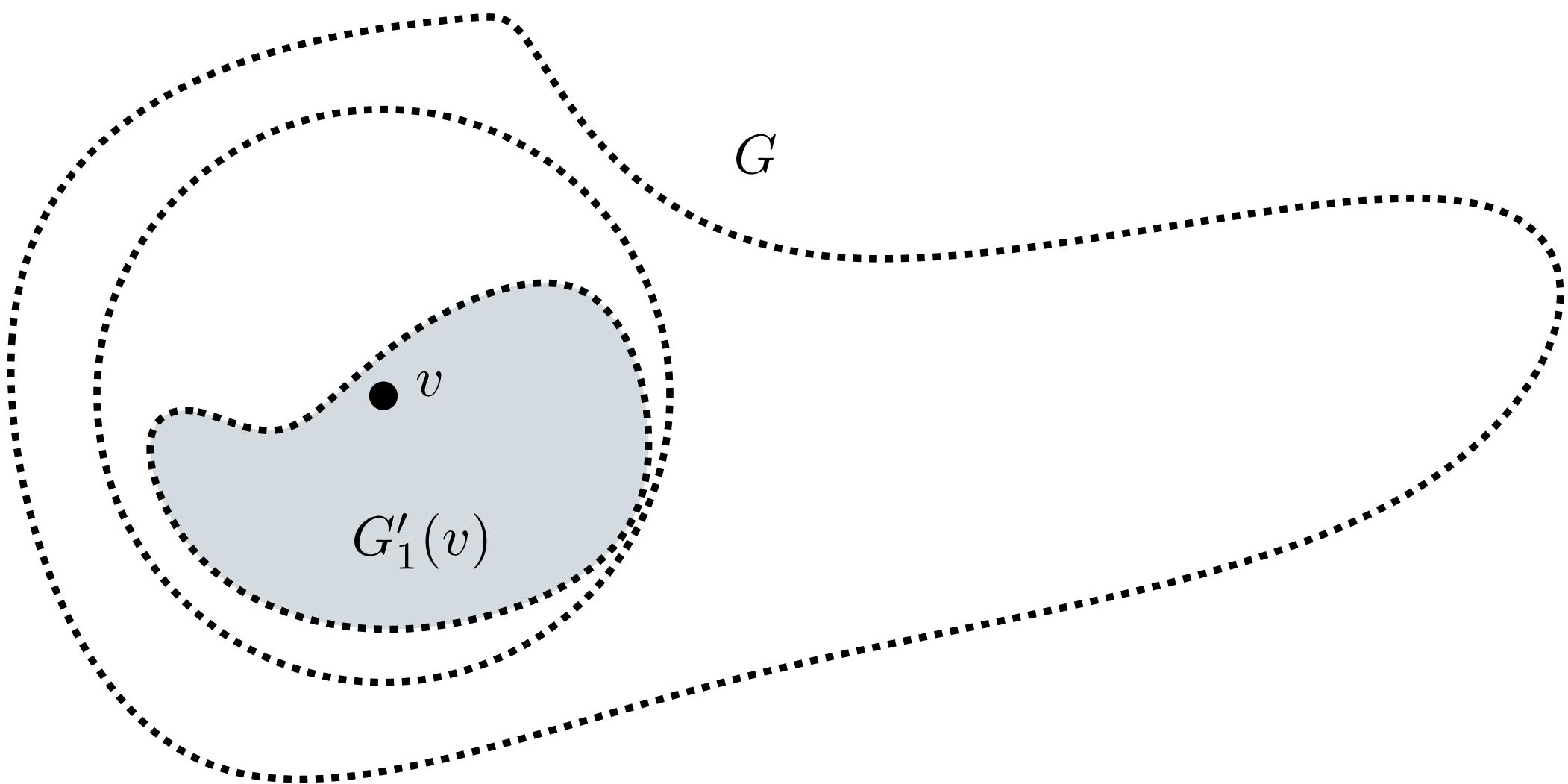
Lemma 2: Find Hall subgraph $H_0 \subseteq G'_0(v)$.

Distributed Hall's algorithm



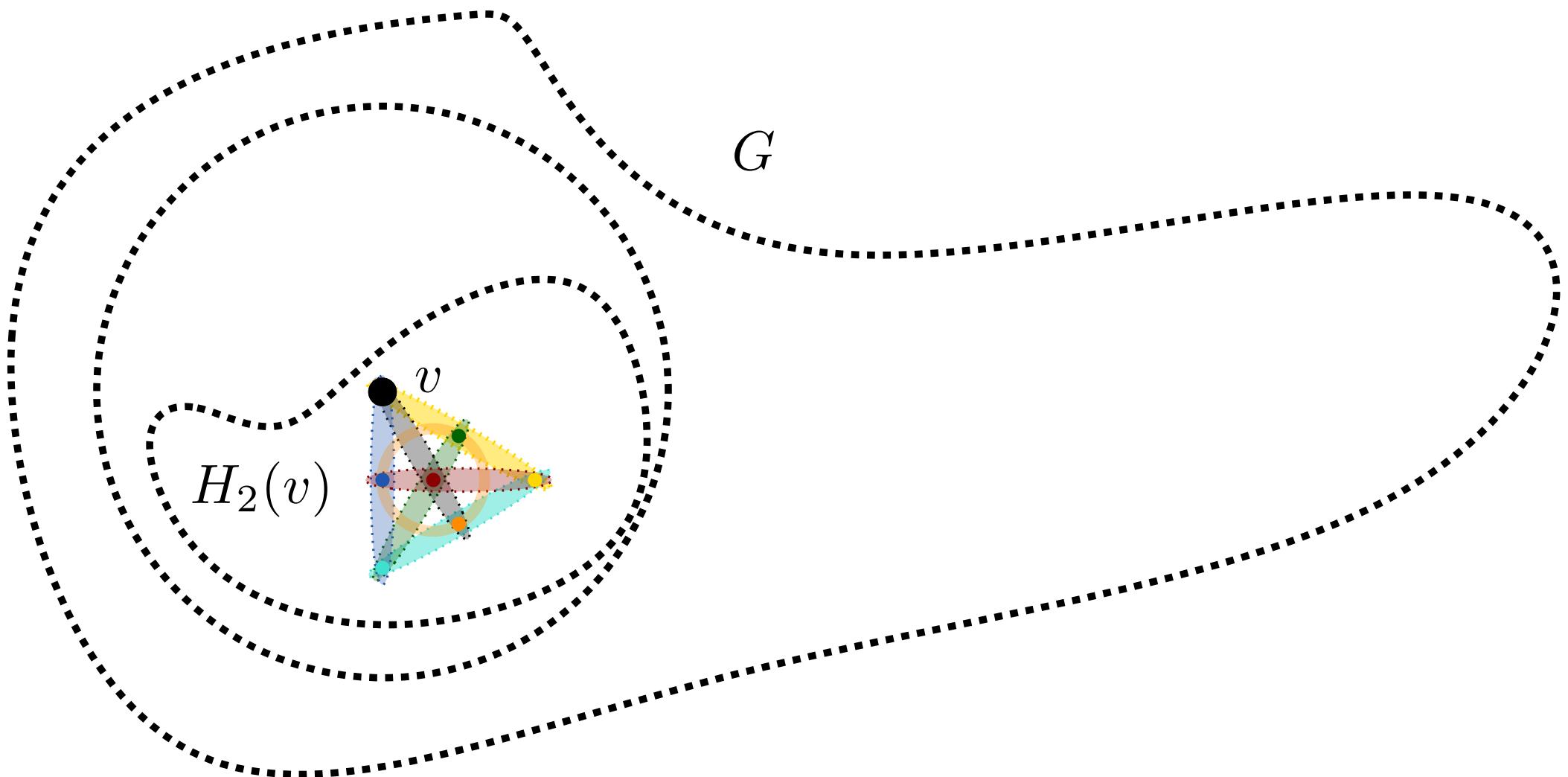
Invariant: $\delta(G_i(v)) > r(G_i(v))$

Distributed Hall's algorithm

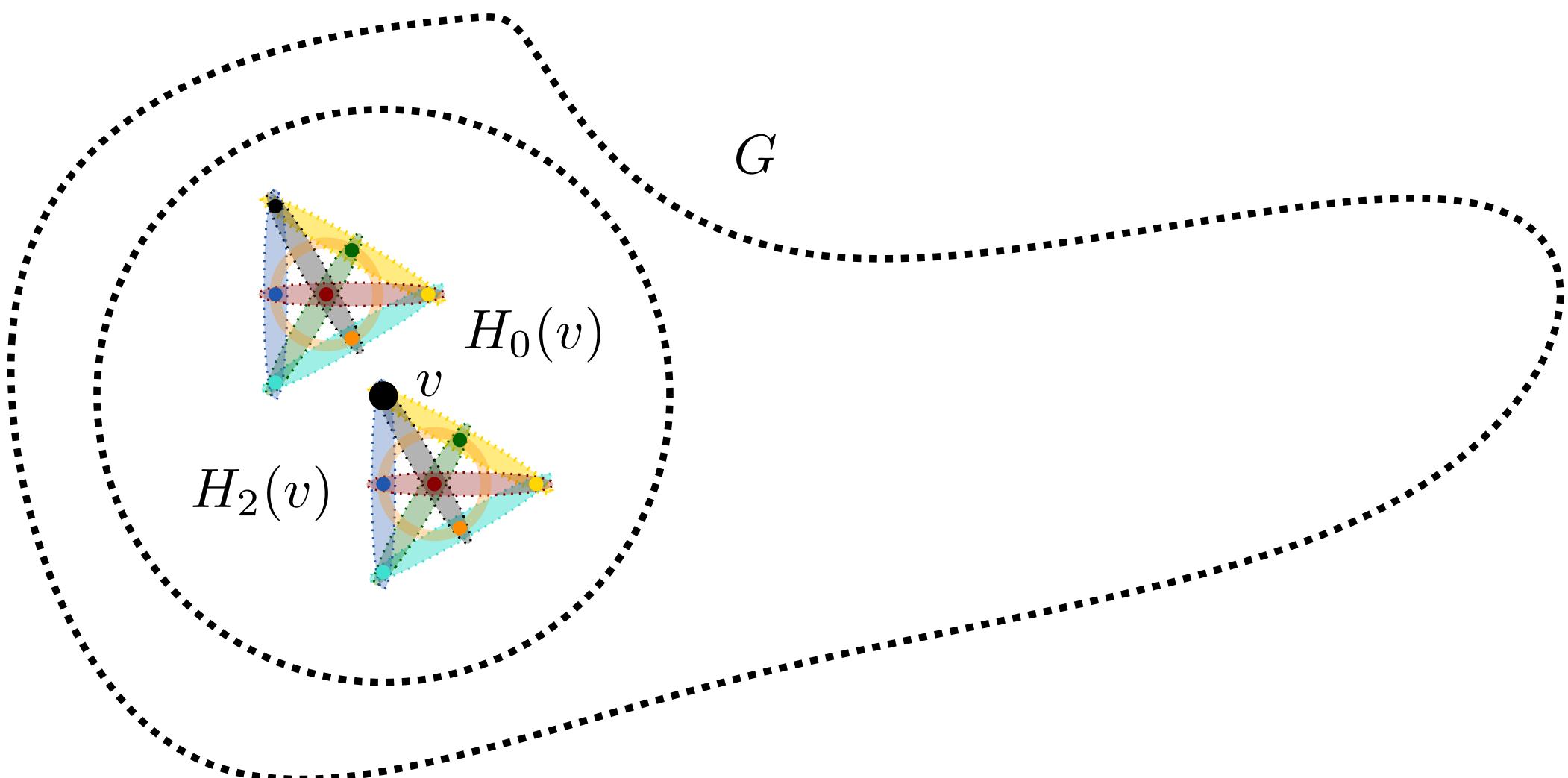


Lemma 1: Find a subgraph $v \in G'_1(v) \subseteq G_1(v)$ with $|V'| \geq |E'|$.

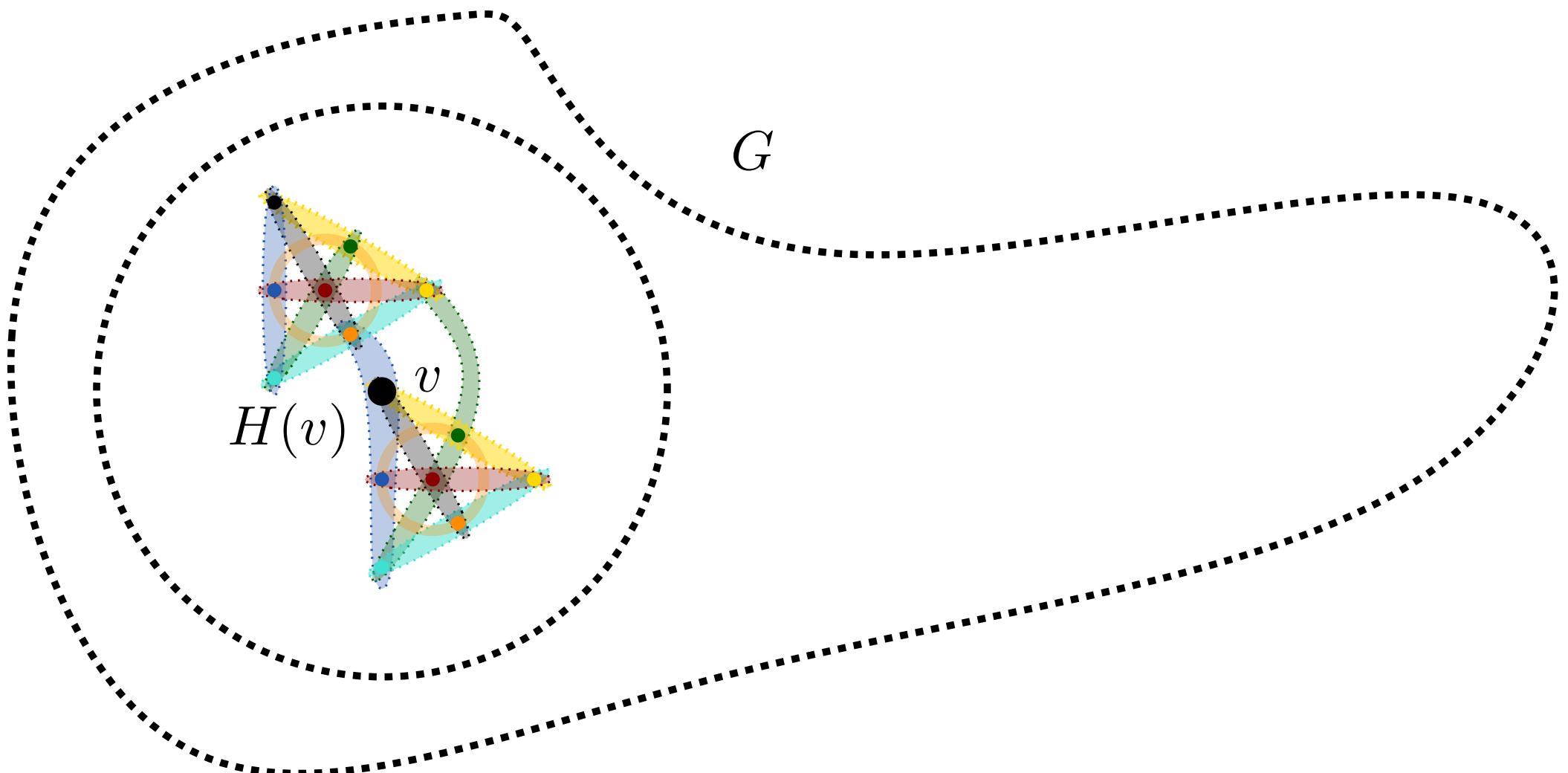
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Problem: Hypergraph sinkless orientation (HSO)

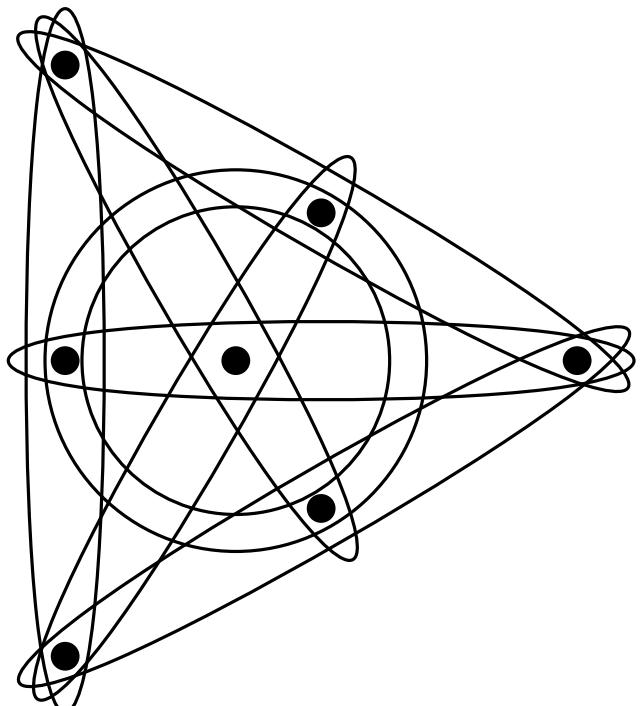
Input: A hypergraph H with min. degree δ and max. rank r .

Output: An orientation of the hyperedges such that every vertex has at least one outgoing hyperedge.

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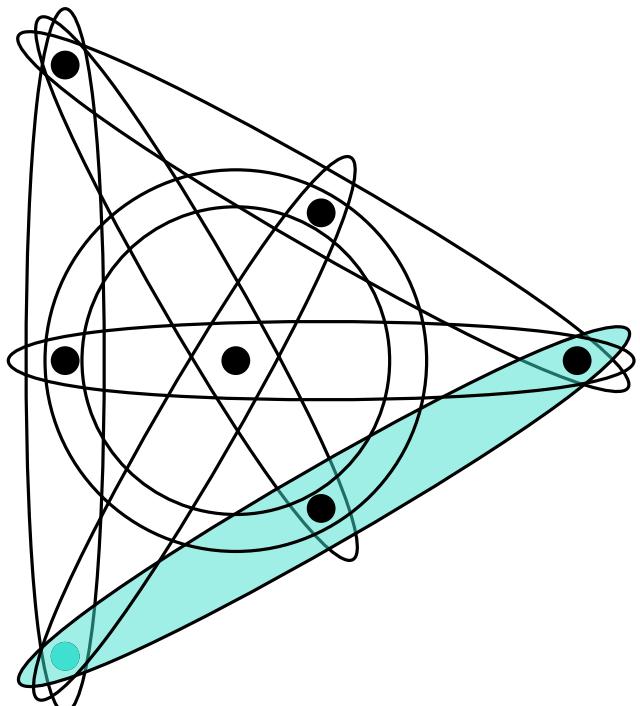
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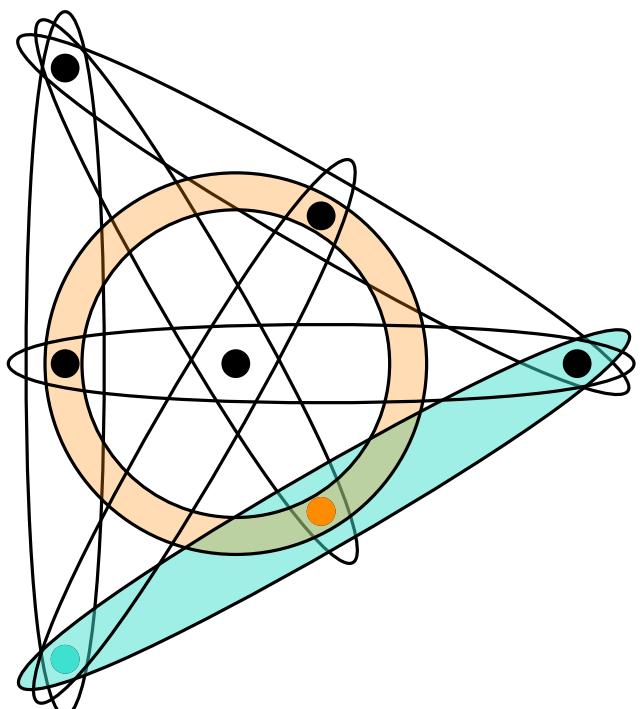
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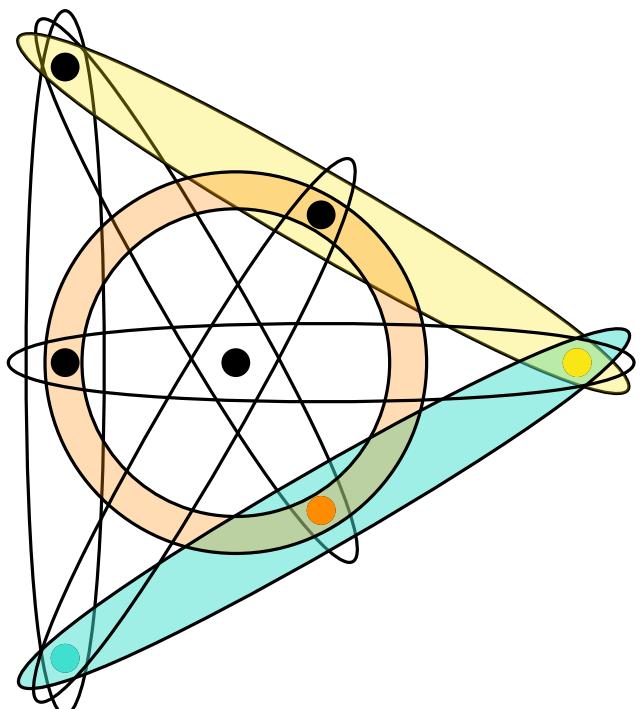
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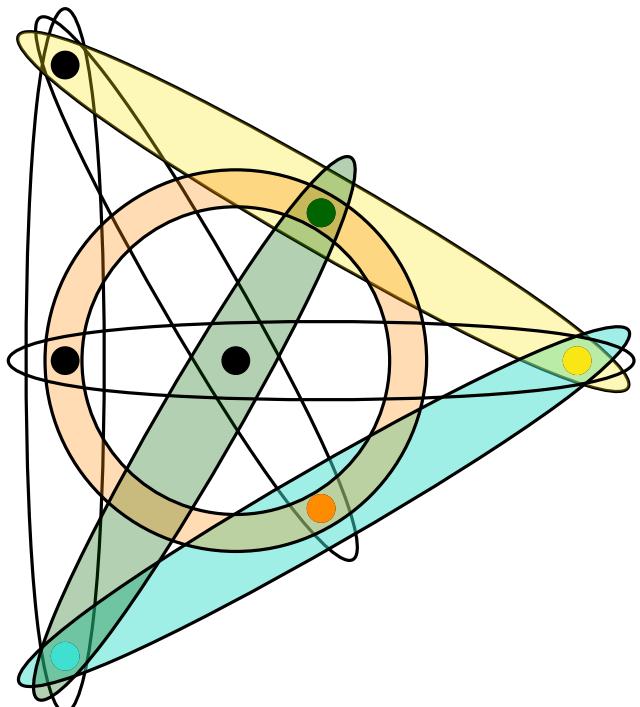
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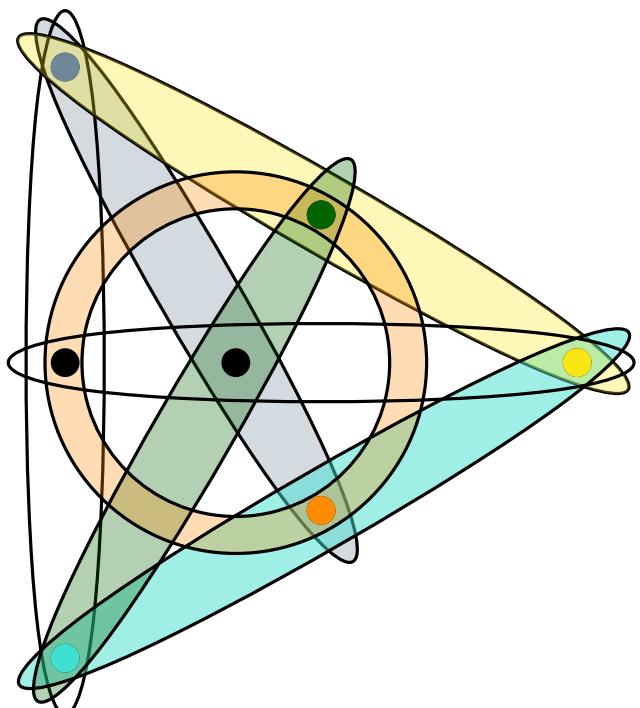
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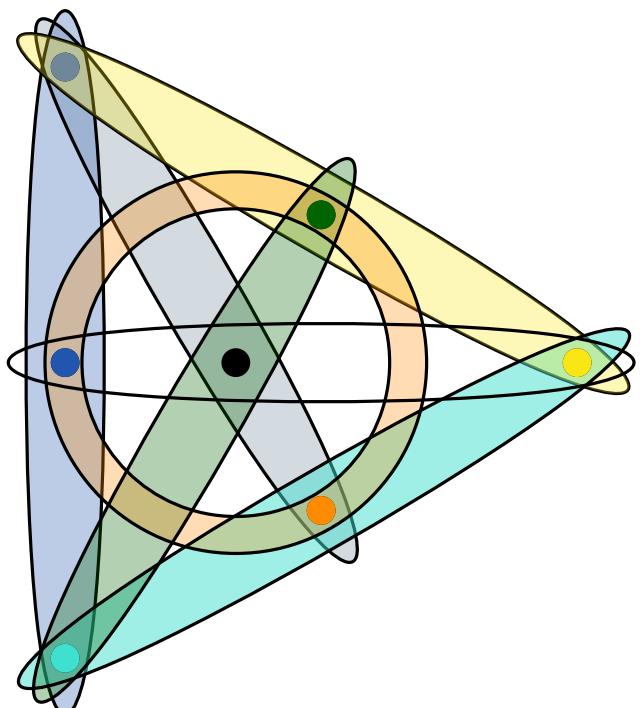
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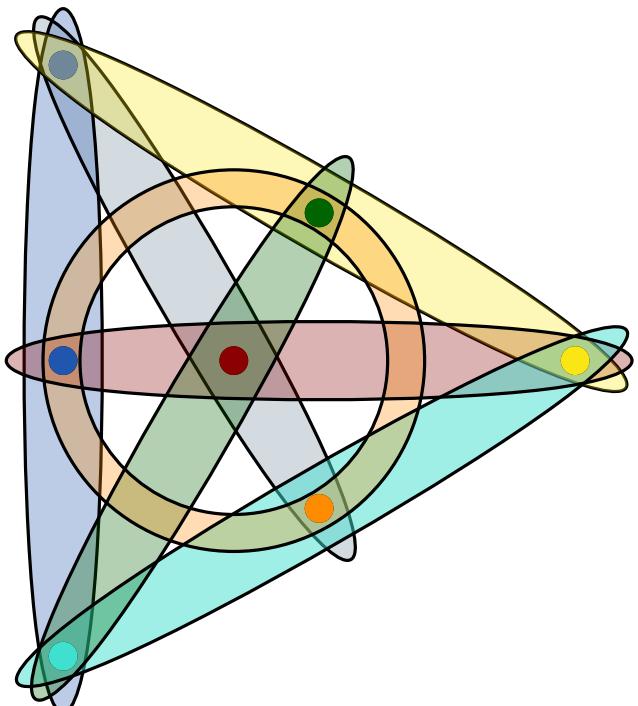
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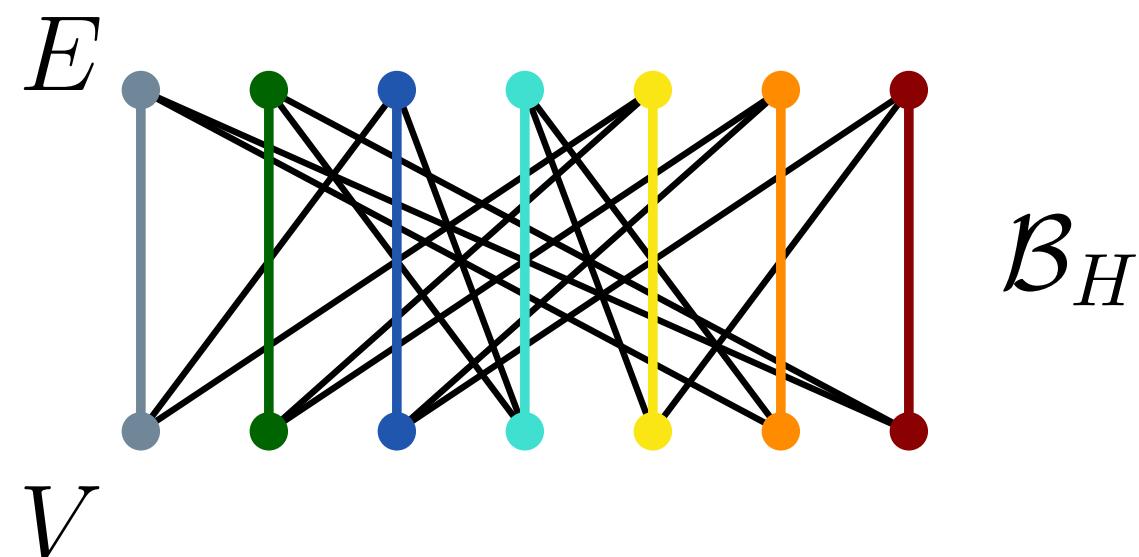
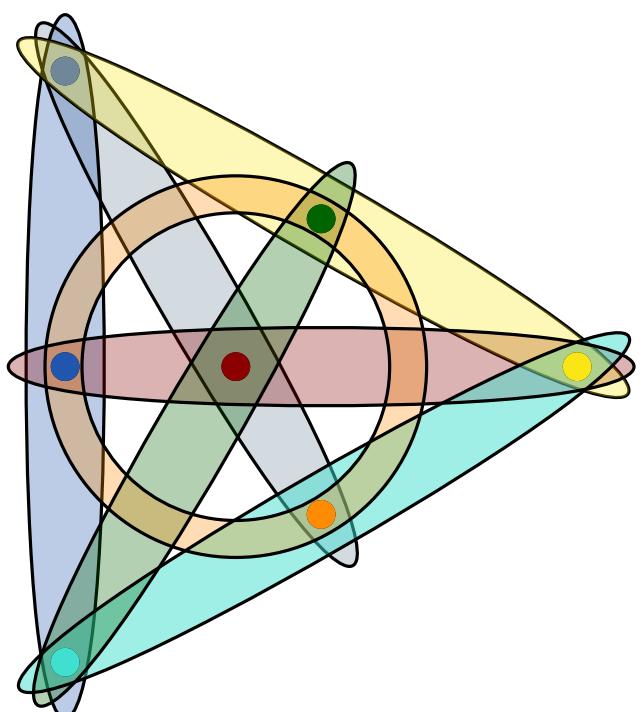
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Output: A node saturating matching in $\mathcal{B}_H = (V, E, F)$.



Deterministic HSO algorithm

Sequential algorithm

for $v \in V$:

 Find a local Hall graph $H(v) \ni v$.

 Compute a HSO of $H(v)$.

 Orient the edges in $H(v)$ accordingly.

end for

Orient all remaining hyperedges arbitrarily

Deterministic HSO algorithm

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What happens if we reorient edges?

Orienting edges in a HSO cannot create a sink!

Deterministic HSO algorithm

LOCAL algorithm

for $v \in V$:

 Compute $H(u)$ for all $u \in B_x^G(v)$.

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for $e \ni v$

 Find the Hall graph H^* with the largest index

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Runtime: $2x = \mathcal{O}(\log_{\delta/r} n)$

HSO results

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Algorithms	$\mathcal{O}(\log_{\delta/r} n)$ <small>[new result]</small>	
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[Balliu, Brandt, Kuhn & Olivetti, STOC'22]

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$\delta = r$	$\Omega(n)$ <small>[new result]</small>	

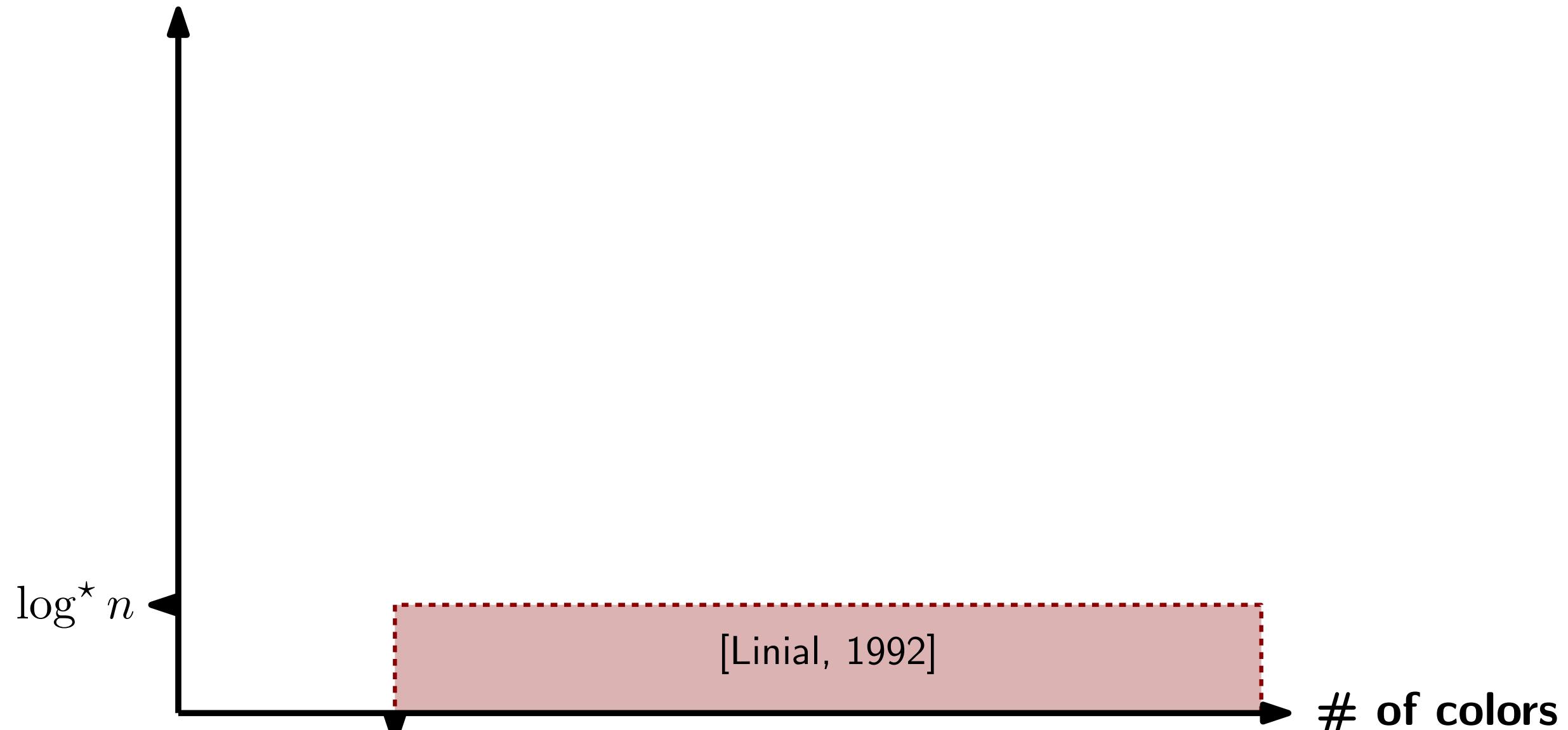
State-of-the-art edge coloring in DetLOCAL for const. Δ

Time complexity



State-of-the-art edge coloring in DetLOCAL for const. Δ

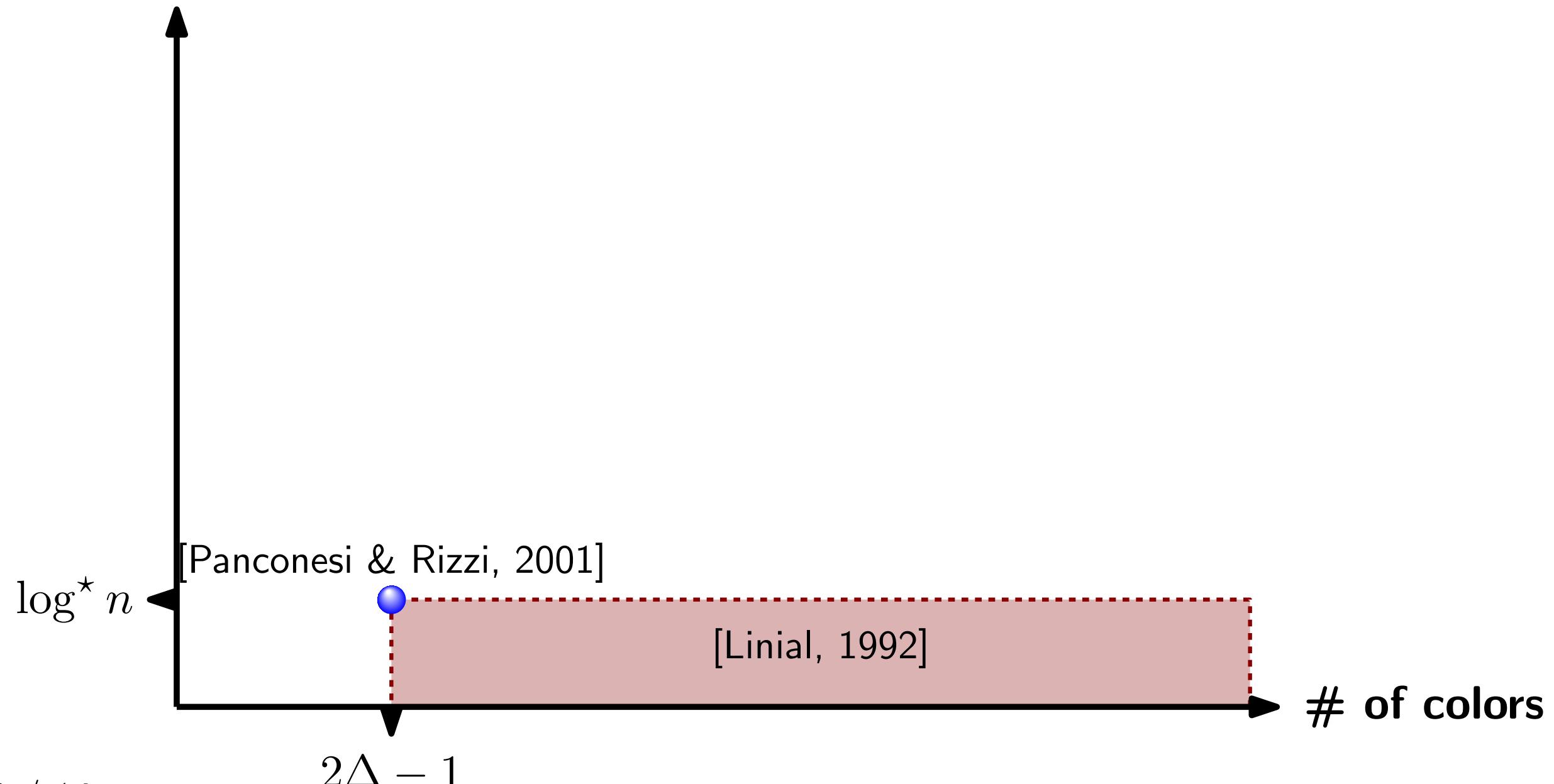
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$2\Delta - 1$

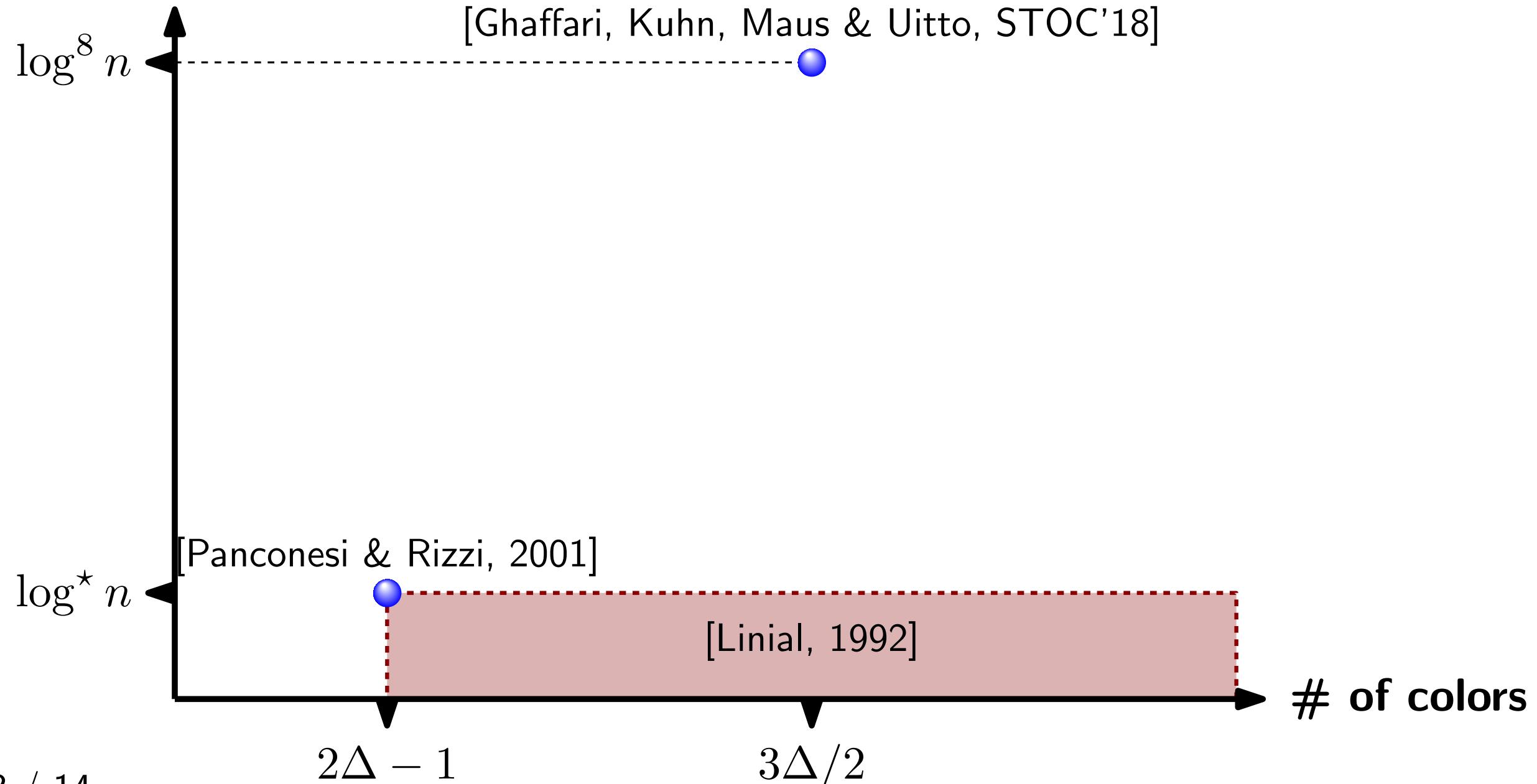
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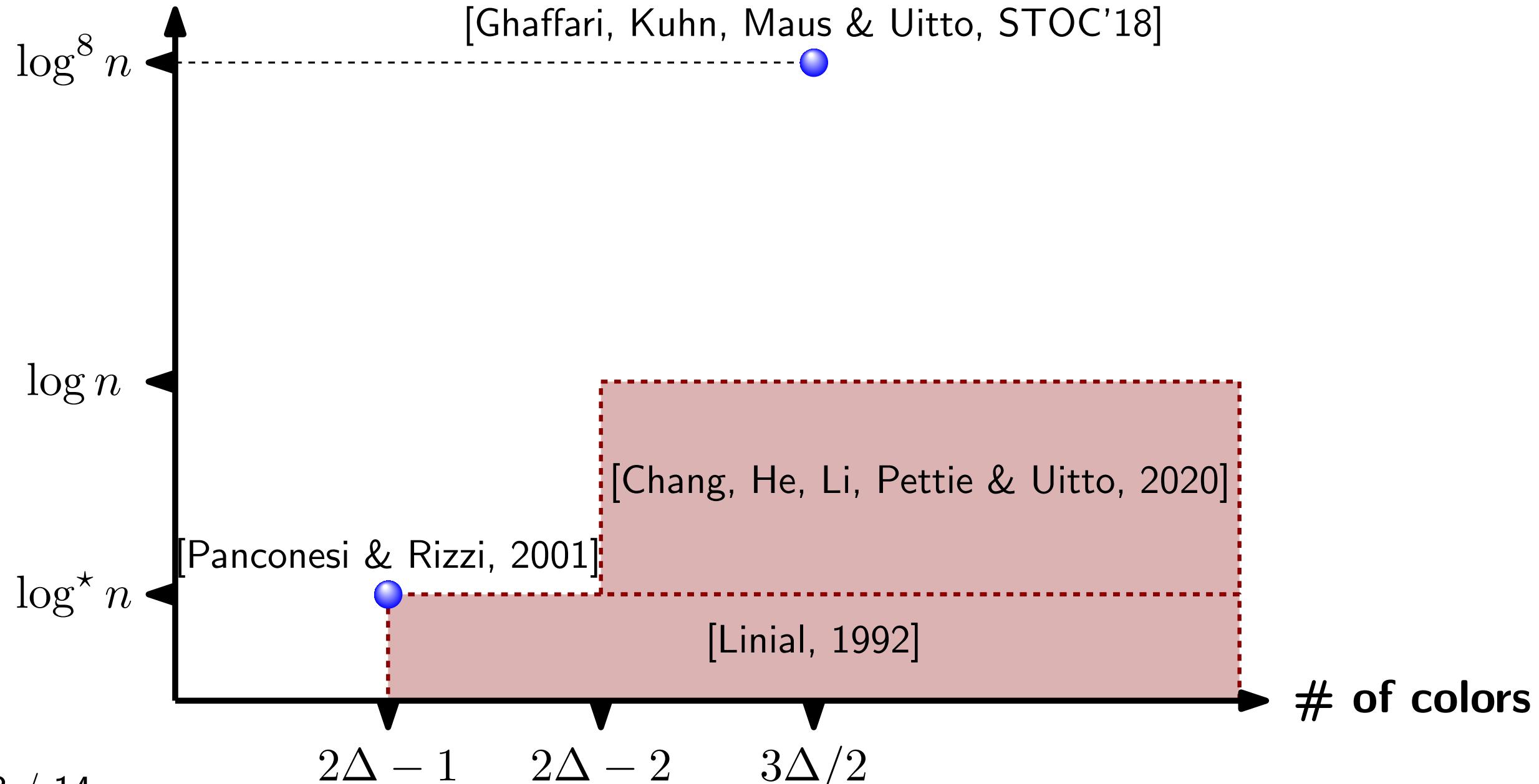
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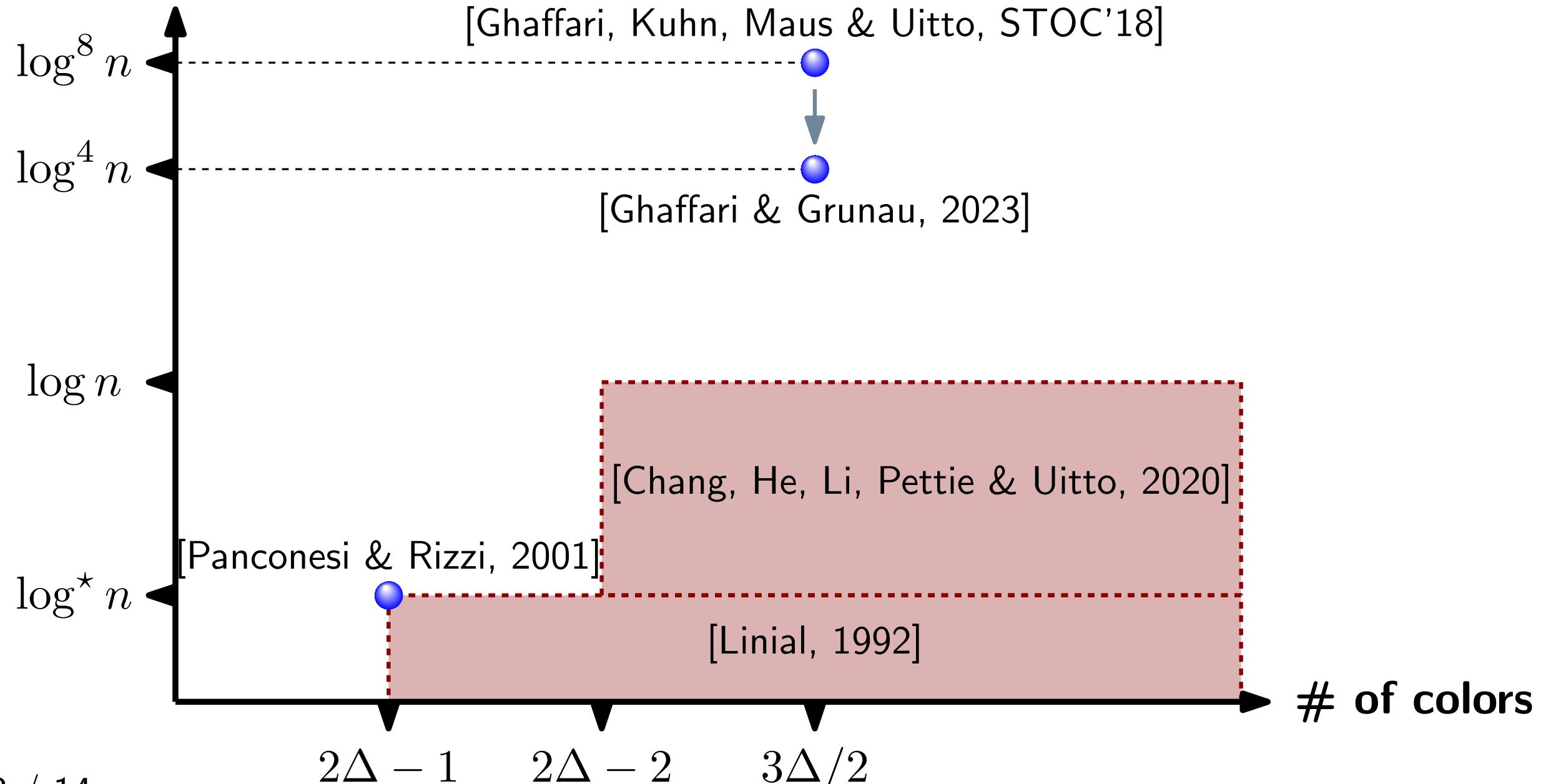
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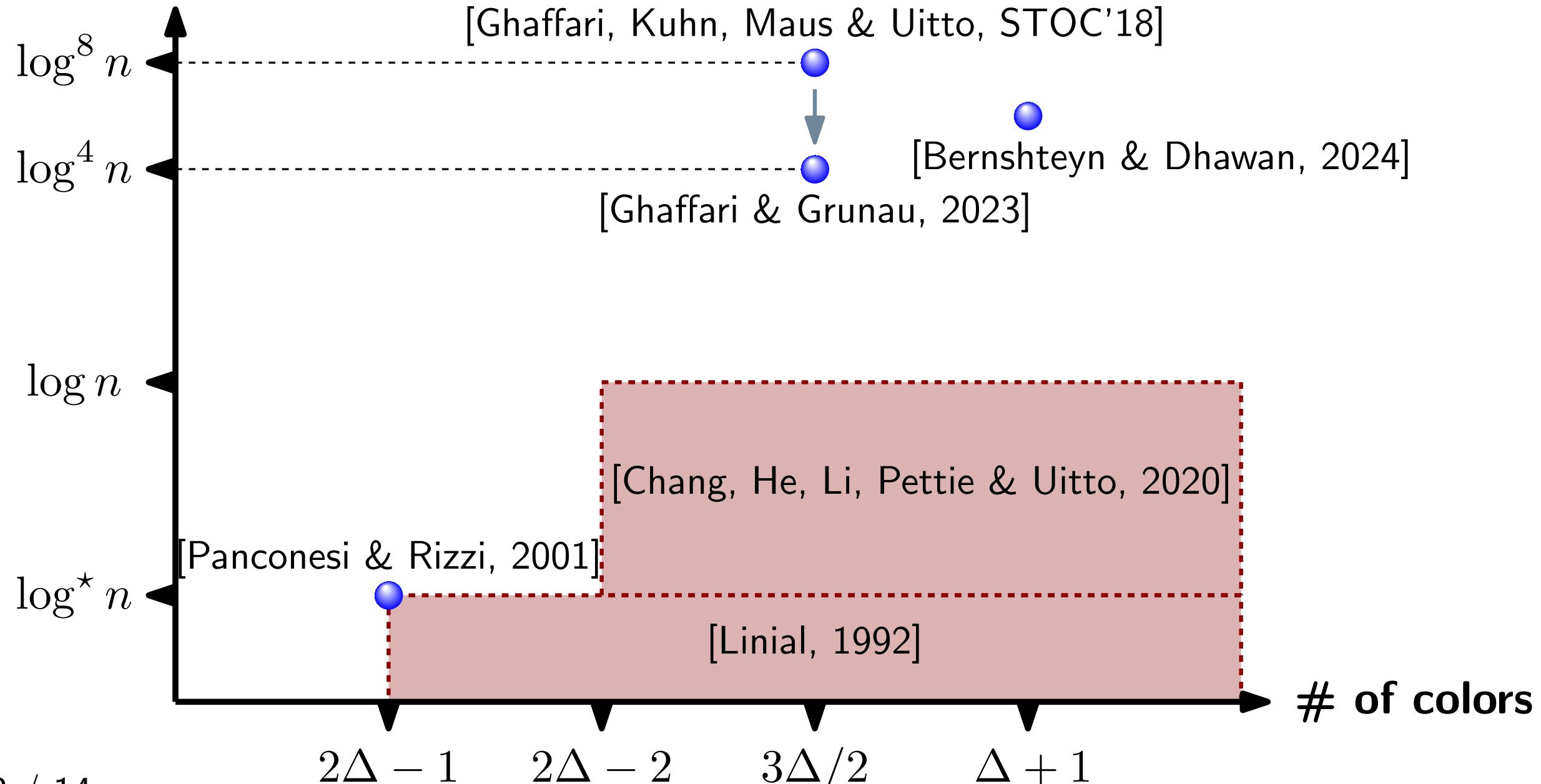
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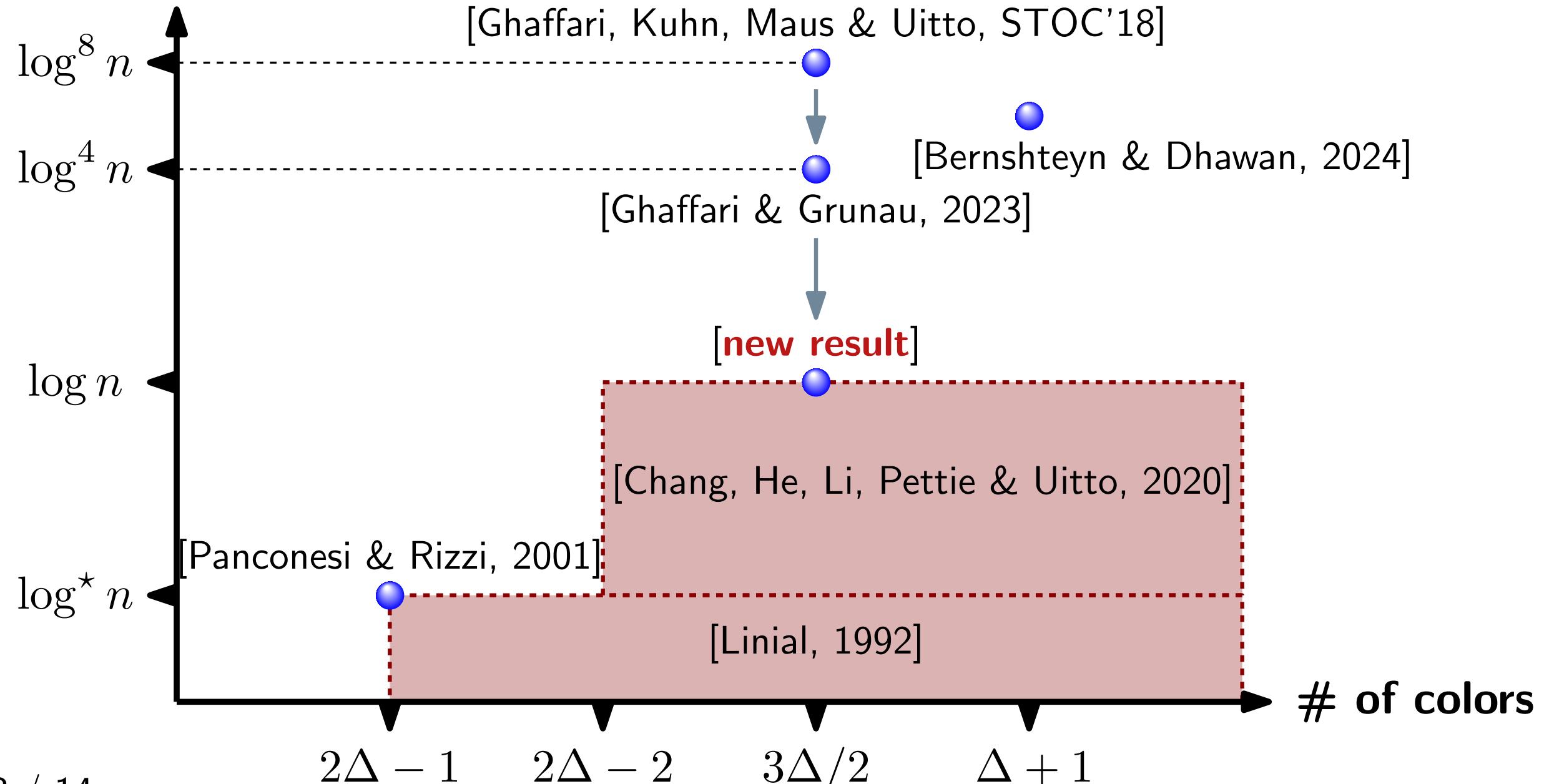
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Final slide

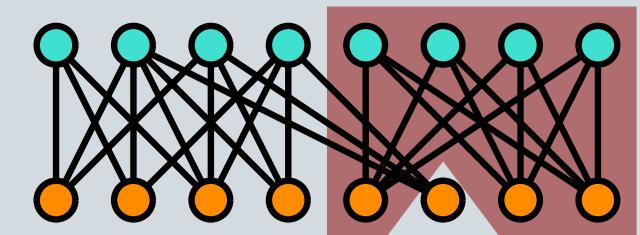
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Design asymptotically optimal algorithms in the LOCAL model

$\Theta(\log n)$

Algorithm design technique

Distributed Hall's Theorem



Application

$3\Delta/2$ -edge coloring algorithm

