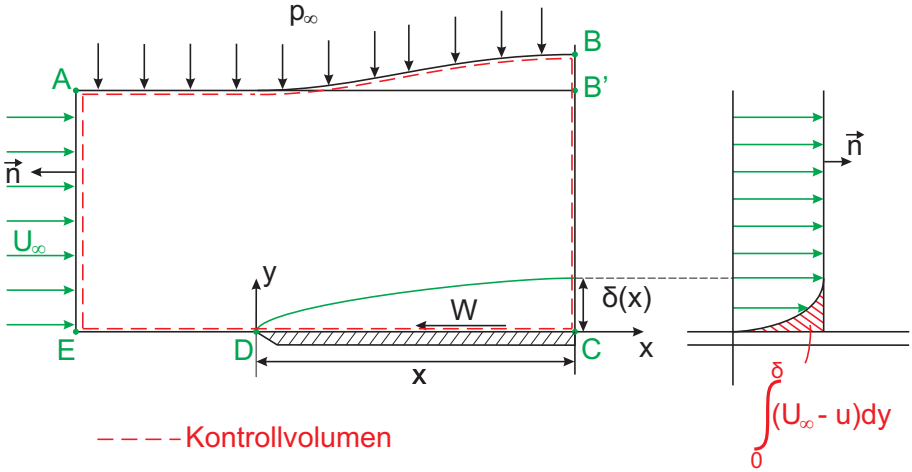
p∞
A
B
B'
n
U∞
y
W
δ(x)
E
D
C
x
x
n
δ
∫ (U∞ - u)dy
0
Kontrollvolumen