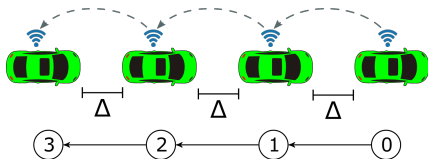


Master thesis: Robust Platooning with binary Controllers - A Sliding Mode Perspective

- **robust control of connected vehicles**
- application e.g. using vehicle platooning



- verification of the results in the laboratory
- contact: Martin Steinberger
- start possible any time
- in cooperation with:
KTH Royal Institute of Technology, Stockholm

