

Visual and LiDAR Perception Systems Design and testing using Automated Driving Toolbox

- Exploring various possibilities of Automated Driving Toolbox:
 - Generation of driving scenarios and algorithm testing using synthetic data
 - Perception with computer vision and LiDAR
 - Sensor fusion and tracking
- Different scenario testing
- Start: Immediately
- Contact: Jasmina Zubača
- E-mail: jzubaca@tugraz.at

